

PDE and Wavelet Techniques for Image Compression

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SCPDE02, Baptist Univ., Hong Kong, Dec 12-15, 2002

Collaborator: Hao-Min Zhou (Caltech)

Reports: www.math.ucla.edu/applied/cam/index.html

or

www.acm.caltech.edu/~hmzhou

Research supported by ONR & NSF

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Wavelet Transforms and PDE based Techniques in Image Processing

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Outline

≠ Introduction & Motivations

≠ ENO-Wavelet Transforms

≠ Application in Image Compression

≠ Total Variation (TV) Model for
Wavelet Thresholding

≠ Conclusion

Motivations

⌘ Wavelets: great impact in image processing

⌘ PDEs: increasingly effective in image processing

Our goal: **combine best of both techniques**

Introduction

Typical image processing tasks:

- ✂ Restoration (denoising, deblurring)
- ✂ Enhancement
- ✂ Compression
- ✂ Segmentation
- ✂ Patent Recognition
- ✂ Still v.s. Video

Applications:

Medical, Biotech, Physical Science, Astronomy, Law
Enforcement, Environment, Entertainment, Military,
Chemistry, ...

Introduction

Wavelets representation (Harmonic analysis)

given $\psi(x) \longrightarrow \psi_{j,k}(x) = 2^{\frac{j}{2}} \psi(2^j x - k) \longleftarrow$ Orth. basis

$$f(x) = \sum c_{j,k} \psi_{j,k}(x), \quad c_{j,k} = \int f \psi_{j,k} \quad \begin{matrix} \swarrow & \searrow \\ \text{Low Freq.} & \text{High Freq.} \\ & \text{(average)} \\ & \text{(difference)} \end{matrix}$$

Wavelets in image compression.

Good features:

- Orthonormal basis

- Concentrate energy

- Approximate smooth function efficiently

- High order of accuracy

- Multiresolution

- Fast transform algorithms

- Limitation: Oscillations at discontinuities

Introduction

⌘ PDE s in Image Processing

⌘ New alternative to FFT/wavelets and stat. approaches

⌘ Treats images as piecewise continuous functions connected by edges

⌘ Use PDE concepts: gradients, diffusion, curvature, level sets

⌘ Variational: Euler-Lagrange gives PDE, e.g. TV denoising

$$\begin{array}{ccc} \min \int |\nabla u| & \longrightarrow & \nabla \left(\frac{\nabla u}{|\nabla u|} \right) - \lambda(u - u_0) = 0 \\ \text{s.t. } \|u - u_0\| \leq O & & \end{array}$$

⌘ Advantages:

⌘ Sharper edges,

⌘ better geometric properties

⌘ exploit sophisticated PDE and CFD techniques: Hamilton-Jacobi, shock capturing

Motivations

⌘ Avoiding Gibbs phenomenon:
Oscillations at discontinuities.

⌘ Reason for Gibbs:

Discontinuities \longrightarrow Large high freq.

Truncate high freq. \longrightarrow Destroy discontinuities

\longrightarrow Generate Oscillations.

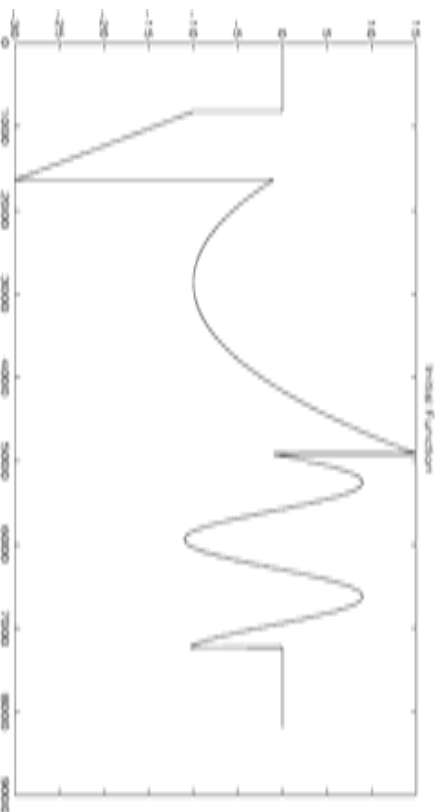
⌘ Examples:

- Fourier: well known.
- Wavelets: Better (more local) but still there.

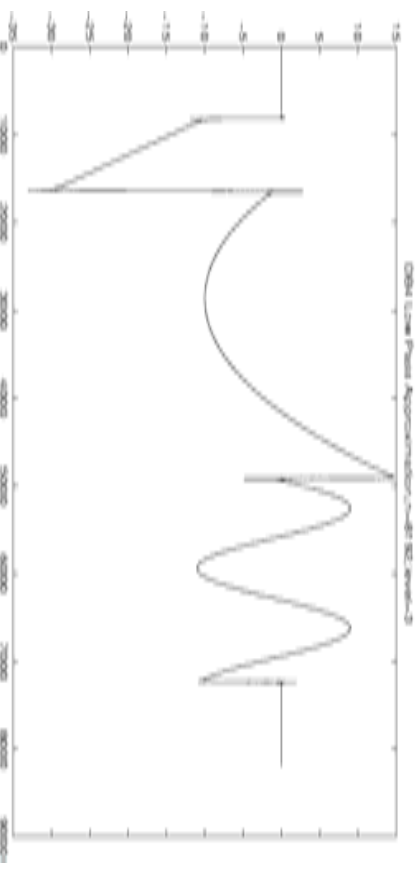


Gibbs oscillations at a discontinuity

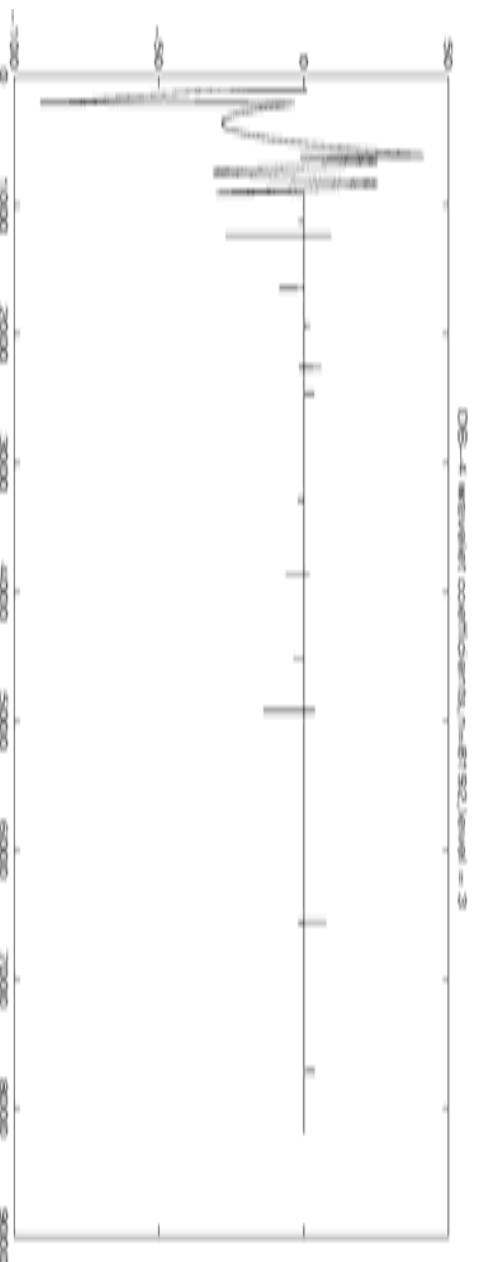
Motivations ...



Original function

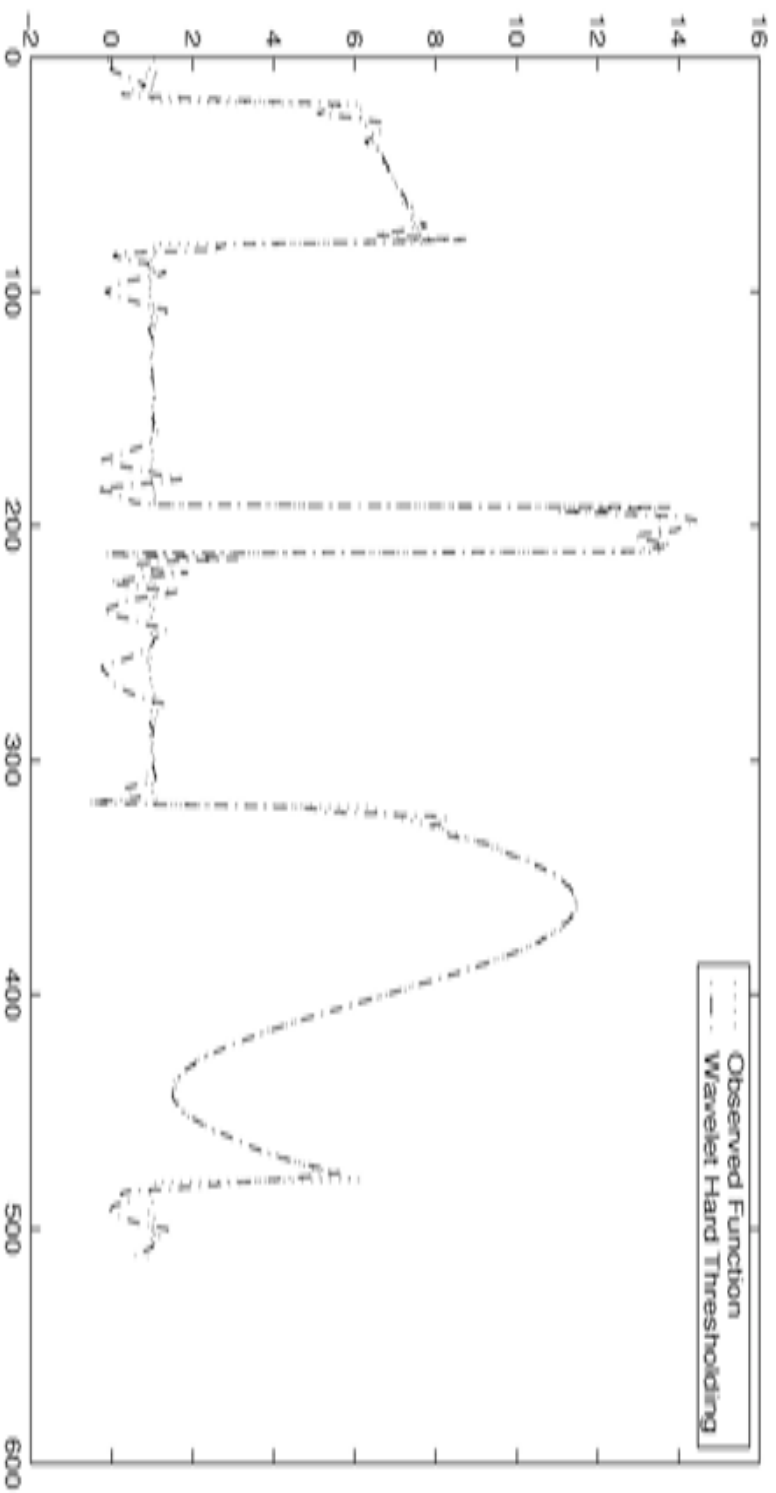


3-level DB4 approximation



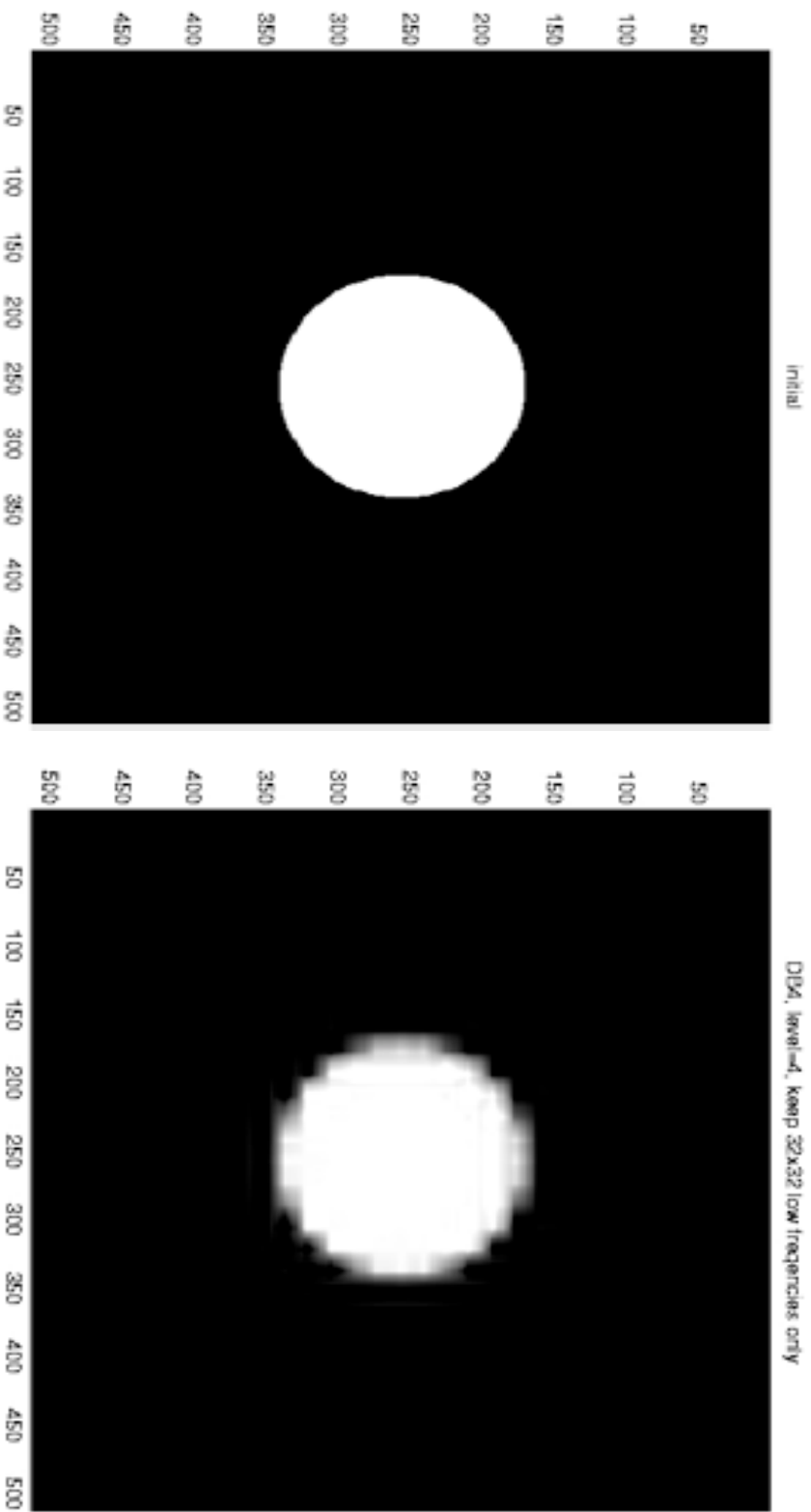
3-level DB4 coefficients, large high frequencies corresponding to jumps

Motivations ...



Gibbs for noisy data

2-D Gibbs



Original 2-D Function

4-level DB4, Gibbs
oscillations at edges

Gibbs leads to poor results

- ✗ Approximation error
- ✗ Denoising: Edge smearing and oscillations
- ✗ Compression: worse with same ratio

Motivations

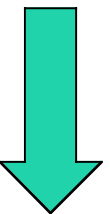
‡ Using PDE techniques in wavelets:

‡ Modify wavelet transforms: Adaptive ENO-Wavelet Transforms (ENO schemes are very popular and successful in CFD), such that no large high freq. coefficients are generated.

‡ Modify the standard wavelet coefficients: Total-Variation (TV) based wavelet image compression (TV leads to nonlinear PDEs)

Outline

≠ Introduction & Motivations



≠ **ENO-Wavelet Transforms**

≠ Application in Image Compression

≠ Total Variation (TV) Model for
Wavelet Thresholding

≠ Conclusion

Topic 1

ENO-wavelet transform and its
application in image compression

Goals

Modify standard wavelet transforms to have the following properties:

1. Essentially Non-Oscillatory (ENO).
2. Retain Pyramidal filtering framework.

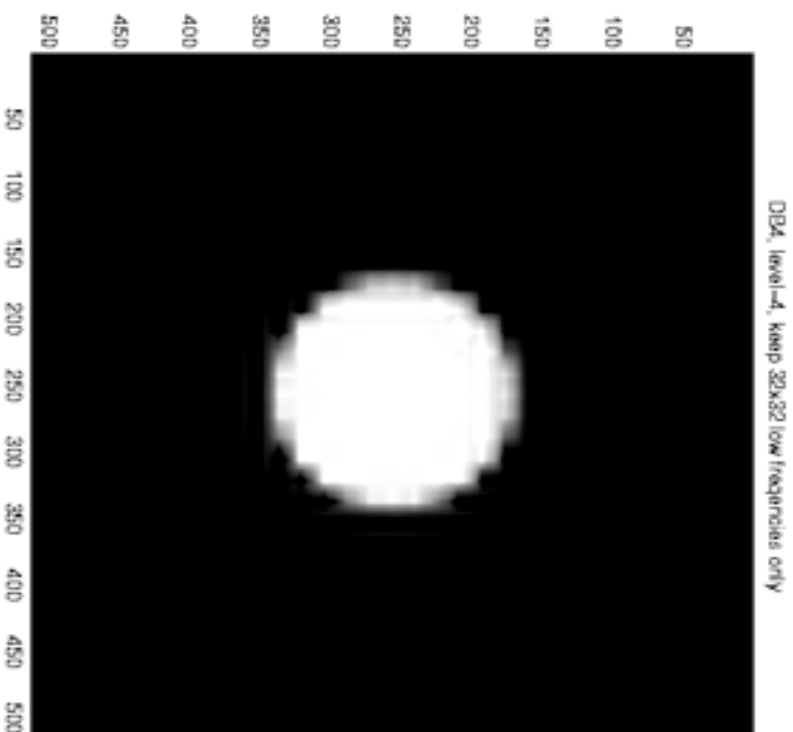
— *Functional replacement of existing wavelet transforms*

3. Error bound depends only on derivatives away from discontinuities.

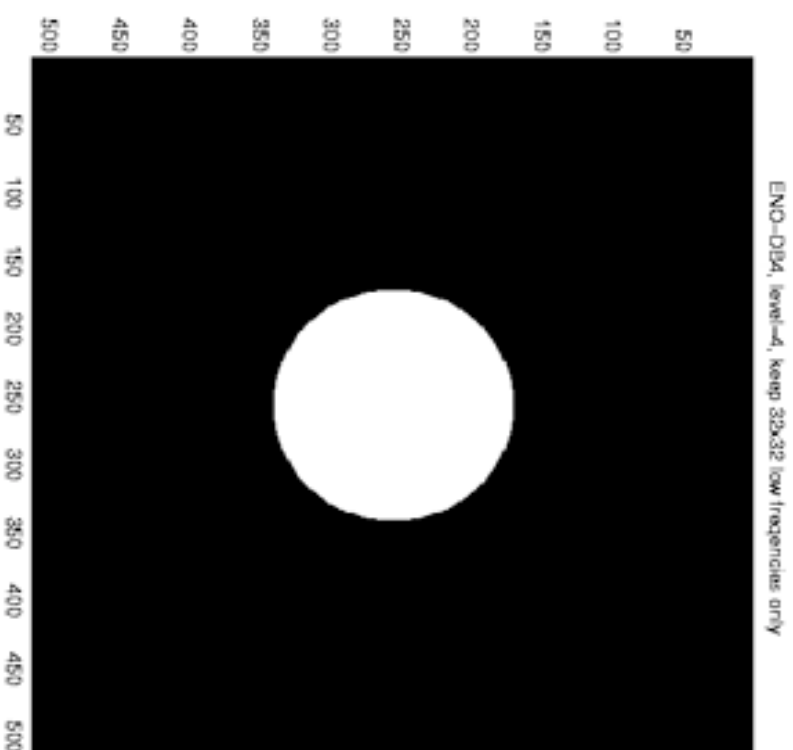
4. Minimal extra cost and storage.

— *Proportional to number of discontinuities.*

Goals ...

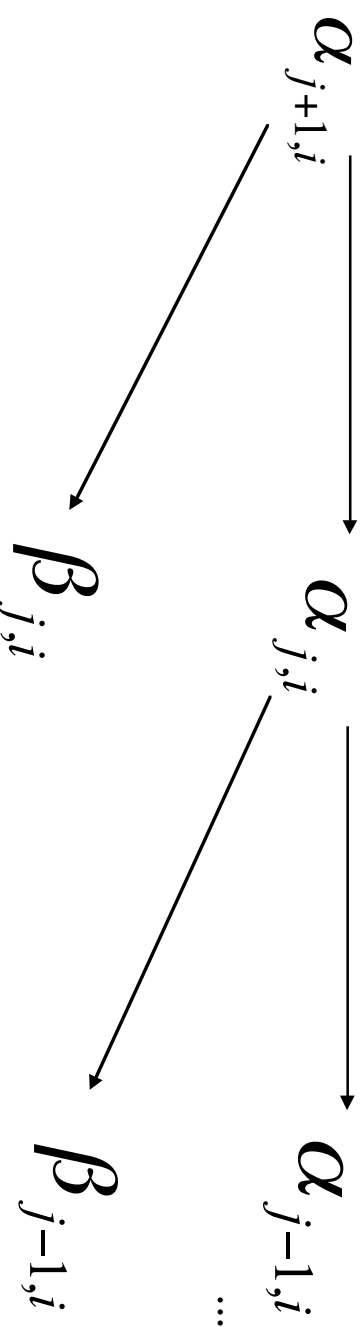


DB4, 4-level



ENO-DB4, 4-level

Pyramidal Wavelet Transforms



Consider p vanishing moments wavelets: $p=(l+1)/2$

⚡Low freq. (average):

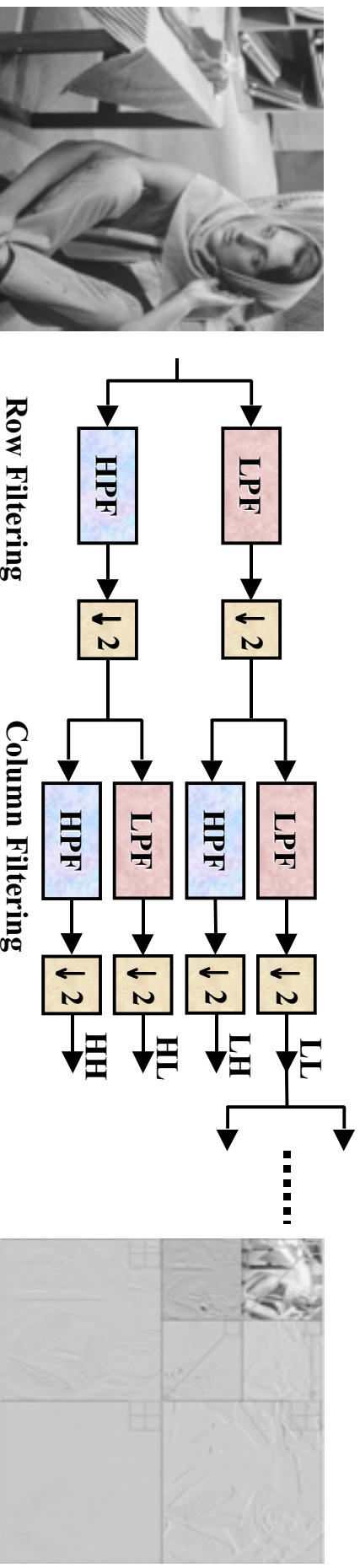
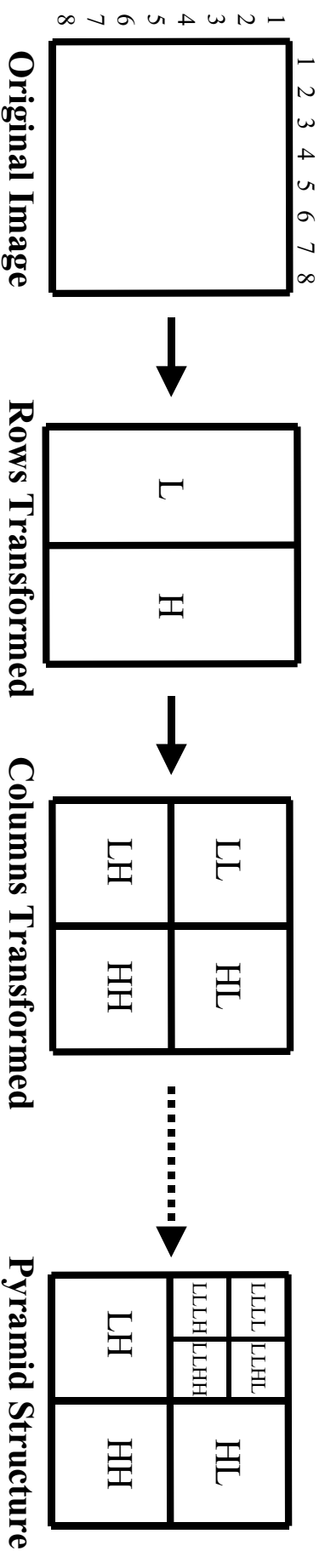
$$\alpha_{j,i} = \sum_{s=0}^l c_s \alpha_{j+1,2i+s}$$

⚡High freq. (p -th order deriv.):

$$\beta_{j,i} = \sum_{s=0}^l h_s \alpha_{j+1,2i+s}$$

⚡Jump in α_{j+1} \longrightarrow **Large** β_j

Wavelets



Approaches

• All linear transforms:

- Gibbs Oscillations
- Must use data-adaptive nonlinear transforms

• Thresholding (Hard and Soft):

- Donoho, DeVore, Daubechies
- Limitation: Complicated data structure to record locations of large high freq.

• Geometry and Wavelets:

- Special basis to represent discontinuities
- Candes and Donoho: Ridgelets and Curvelets.
- Mallat and Collaborators: Bandelet

Approaches ...

- Lower the order of filter at discontinuities:

 - Claypoole, Davis, Sweldens, Baraniuk[99]: Adaptive lifting

 - Limitation: lower the order of accuracy

- ENO one-sided approximation:

 - Harten (93,94)

 - At each point, adaptively form interpolation polynomial

 - Never differencing crossing discontinuities.

 - Limitation:

 - Difficult for pyramidal wavelet transforms

 - Need function values to form divided difference table at each point

 - More extra cost

- Cohen and collaborators: some recent advances

Approaches ...

• ENO-wavelets:

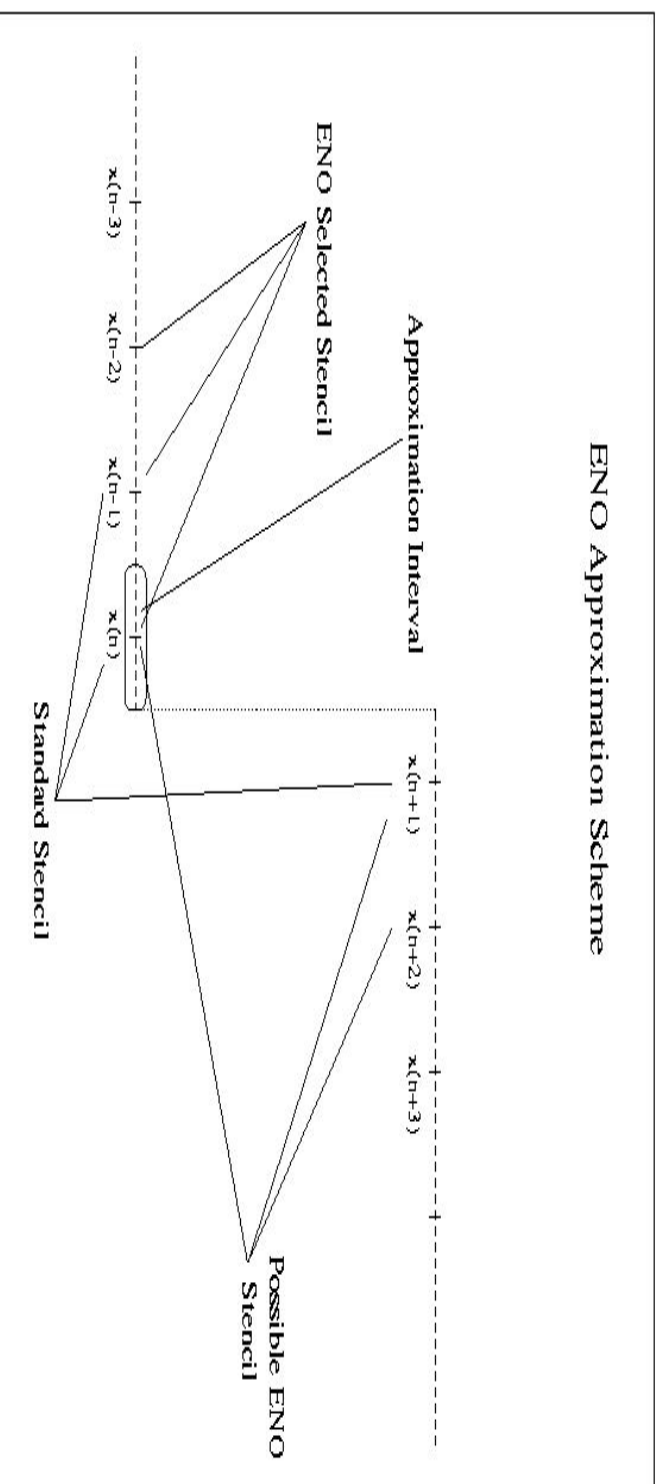
• Do not want to change filters

• Main idea: Change data adaptively

• Make use of ENO's one-sided information idea

• Goal: Do not generate large high frequency coef.

The ENO Idea



⌘ ENO: invented by Harten, Engquist, Osher, Chakravarthy (87)

⌘ Use one-sided information

⌘ Newton divided differences to select smoothes stencil

⌘ Very popular and successful in shock capturing and CFD

The ENO-wavelets Idea

Assume:

- Know location of discontinuities

- Discontinuity Separation Property (DSP):

 - Two consecutive jump points separated by $l+3$ data points

Idea:

- Use extrapolation from smooth side of jumps

- Use same filters, but applied to smooth data

Must take care of

- Retain accuracy order p

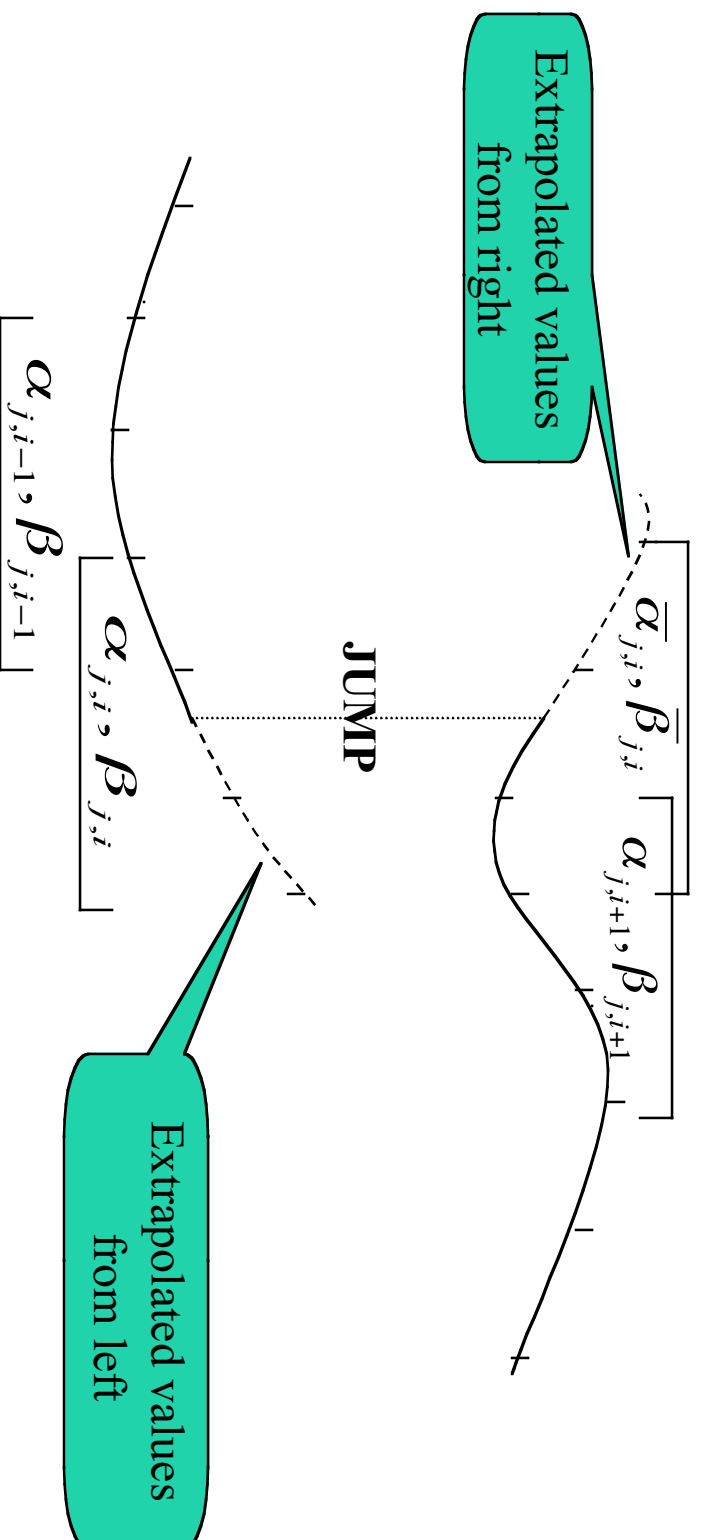
- Minimal extra cost and storage

- Invertibility: able to recover the original data

Direct Function Extrapolation

From left side \longrightarrow Values $\alpha_{j+1,m}$

From right side \longrightarrow Values $\bar{\alpha}_{j+1,m}$

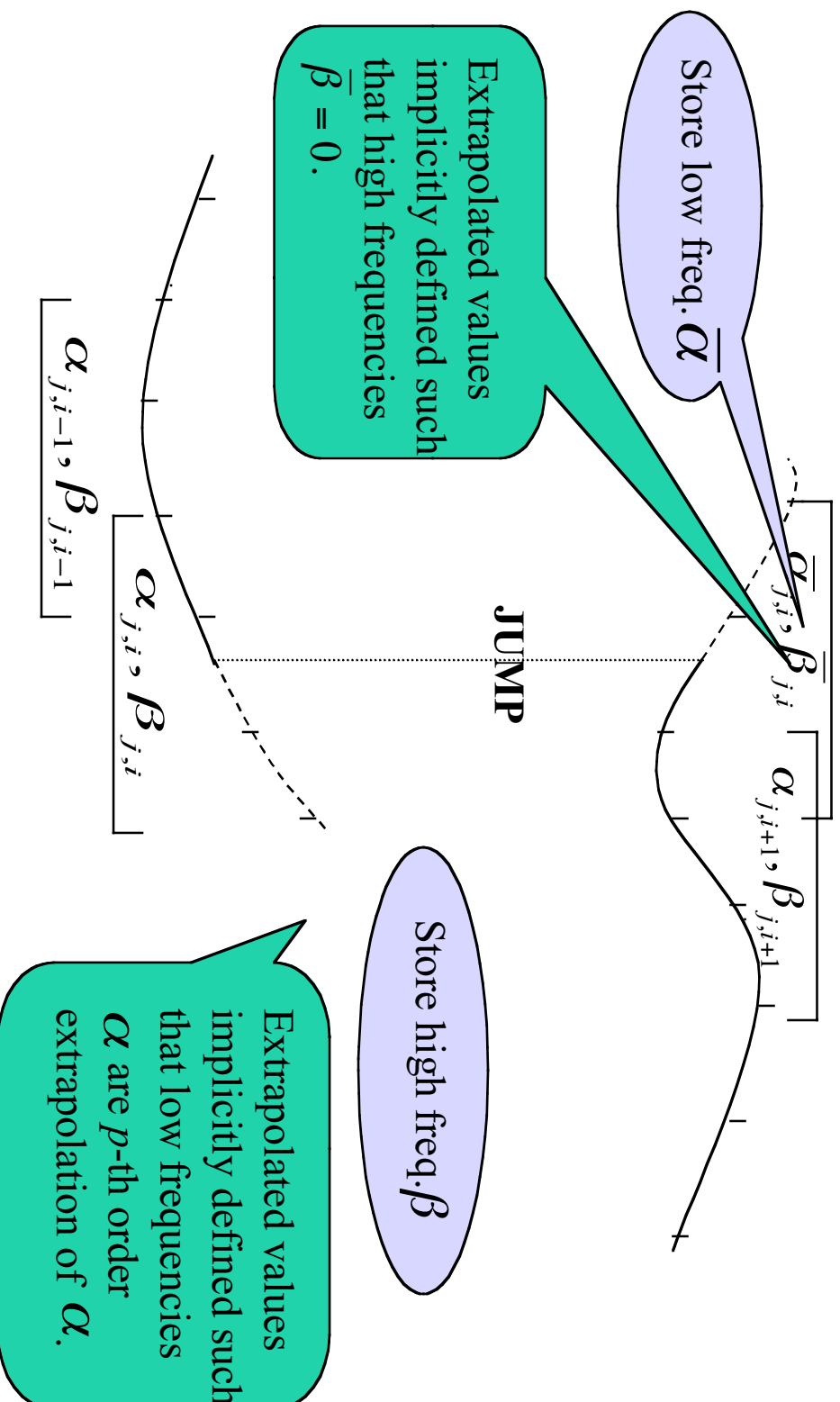


Apply same filters to smooth data on both sides

Problem: double storage at each discontinuity

Coarse Level Extrapolation

≠ Extrapolate coarse level coefficients to determine the fine level values.



Example 1

$$\text{Data: } \begin{pmatrix} 1 & 1 & 1 & 2 & 2 & 2 \end{pmatrix}$$

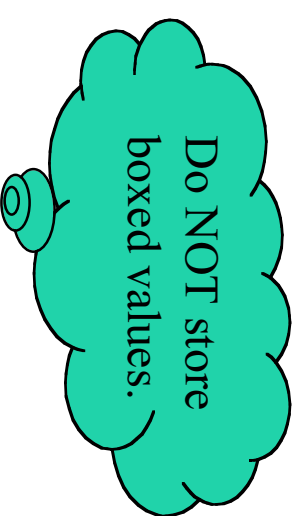
$$\text{Standard Haar: } \alpha = \left(\frac{2}{\sqrt{2}} \quad \frac{3}{\sqrt{2}} \quad \frac{4}{\sqrt{2}} \right), \beta = \left(0 \quad -\frac{1}{\sqrt{2}} \quad 0 \right)$$

Standard linear approximation:

$$\begin{pmatrix} 1 & 1 & \frac{3}{2} & \frac{3}{2} & 2 & 2 \end{pmatrix}$$

ENO-Haar:

$$\text{Extrapolation: } \begin{pmatrix} 1 & 1 & 1 & x & 2 & 2 & 2 \end{pmatrix}$$



$$\text{Coefficients: } \alpha = \begin{pmatrix} \frac{2}{\sqrt{2}} & \frac{\sqrt{2}}{2} & \frac{4}{\sqrt{2}} \end{pmatrix}, \beta = \begin{pmatrix} \boxed{0} & 0 \end{pmatrix}$$

Store:

$$\alpha = \begin{pmatrix} \frac{2}{\sqrt{2}} & \frac{4}{\sqrt{2}} & \frac{4}{\sqrt{2}} \end{pmatrix}, \beta = (0 \quad 0 \quad 0)$$

Linear approximation: same as the initial

Example 2

\mathbb{D} Data: $\begin{pmatrix} 0 & 1 & 2 & 10 & 11 & 12 \end{pmatrix}$

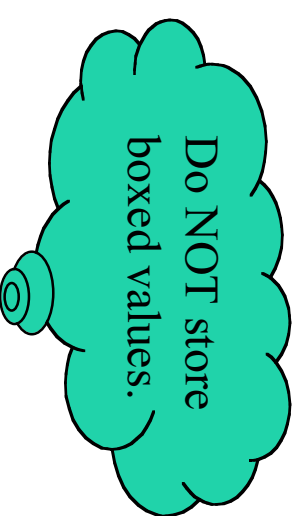
\mathbb{S} Standard Haar: $\alpha = \begin{pmatrix} \frac{1}{\sqrt{2}} & \frac{12}{\sqrt{2}} & \frac{23}{\sqrt{2}} \end{pmatrix}, \beta = \begin{pmatrix} -\frac{1}{\sqrt{2}} & -\frac{8}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \end{pmatrix}$

\mathbb{S} Standard linear approximation:

$\begin{pmatrix} 0.5 & 0.5 & 6 & 6 & 11.5 & 11.5 \end{pmatrix}$

\mathbb{E} ENO-Haar:

\mathbb{E} Extrapolation $\begin{pmatrix} y & 10 & 11 & 12 \\ 0 & 1 & 2 & x \end{pmatrix}$



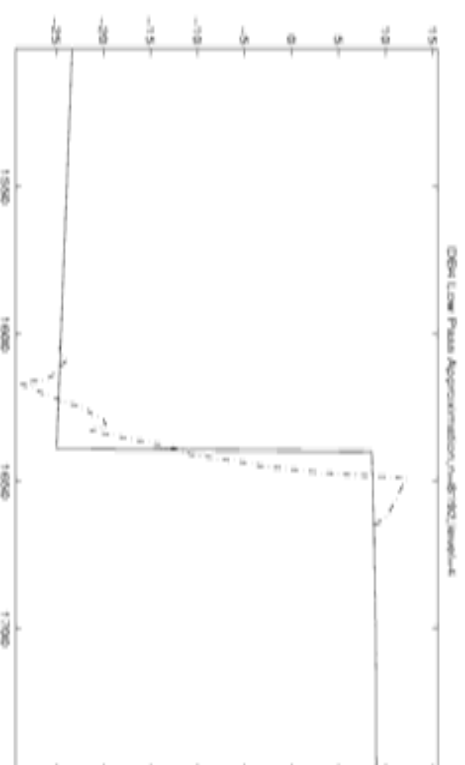
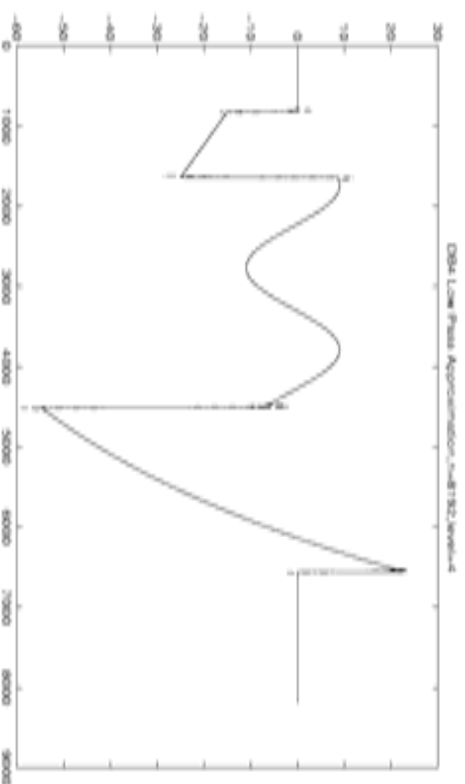
\mathbb{C} oefficients: $\alpha = \begin{pmatrix} \frac{20}{\sqrt{2}} & \frac{23}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & \boxed{\frac{1}{\sqrt{2}}} \end{pmatrix}, \beta = \begin{pmatrix} \boxed{0} & -\frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} & -\frac{3}{\sqrt{2}} \end{pmatrix}$

\mathbb{S} Store:

$\alpha = \begin{pmatrix} \frac{1}{\sqrt{2}} & \frac{20}{\sqrt{2}} & \frac{23}{\sqrt{2}} \end{pmatrix}, \beta = \begin{pmatrix} -\frac{1}{\sqrt{2}} & -\frac{3}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \end{pmatrix}$

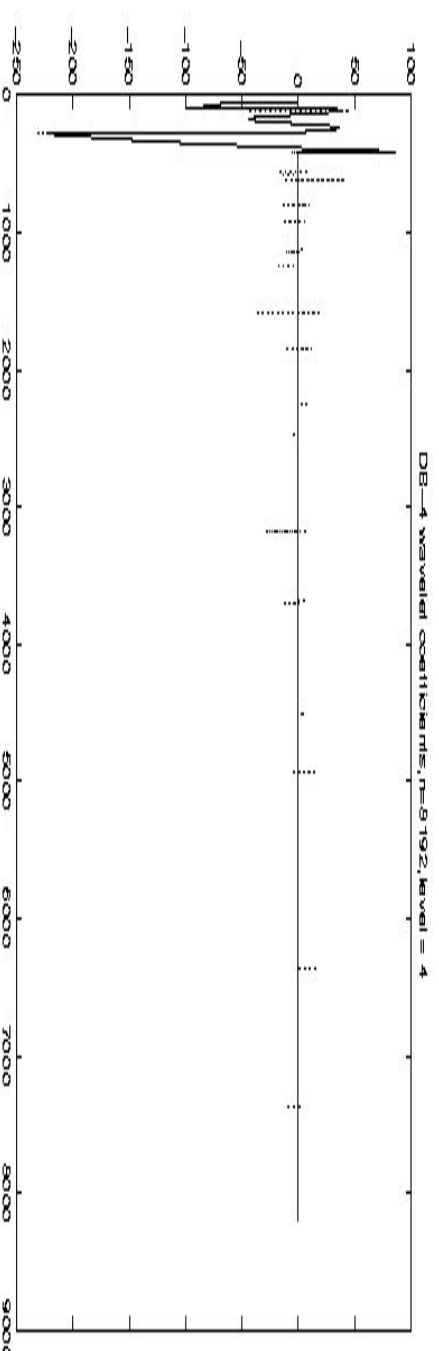
\mathbb{L} inear approximation: $\begin{pmatrix} 0.5 & 0.5 & 0.5 & 10 & 11.5 & 11.5 \end{pmatrix}$

Example of ENO-DB4



4-level DB4 v.s. ENO-DB4

Zoom in at a discontinuity



Large high frequencies in DB4 but not in ENO-DB4

Error Bound and Stability

Error: $f_j(x)$ is the j -th level ENO-wavelet approximation. If $f_{j-1}(x)$ satisfies the DSP, then

$$\|f(x) - f_j(x)\| \leq C(\Delta x)^p \|f^{(p)}(x)\|_{(a,b) \setminus D}$$

Denote $\Delta x = 2^{-j}$

D is the set of discontinuities

Wavelet function has p vanishing moments

The standard error bound depends on $\|f^{(p)}(x)\|_{(a,b)}$

Stability: If $\|f(x) - g(x)\| \leq \varepsilon$ and same set of discontinuities detected, then

$$\|f - g\| \leq O(\varepsilon)$$

Outline of the proof

⌘ Consider individual jump

⌘ Consider three cases

⌘ Direct function extrapolation: preserve order

⌘ Extend $\beta = 0 \longrightarrow (p-1)$ -th order smooth extension

⌘ Extrapolating α 's: extrapolation in wavelet spaces \longrightarrow same order extrapolation in function space

Properties

• Output sequence: same size as input sequence

Half high frequencies and half low frequencies.

• Perfectly invertible

• Extra storage: remember the location of jumps (ENO mapping)

• Cost: Algorithmic complexity remains $O(n)$

Standard cost: $O(nl)$ Extra cost: $O(dl)$, d : number of jumps

Ratio of extra over standard: $O(d/n)$

• Keep p -th order accuracy

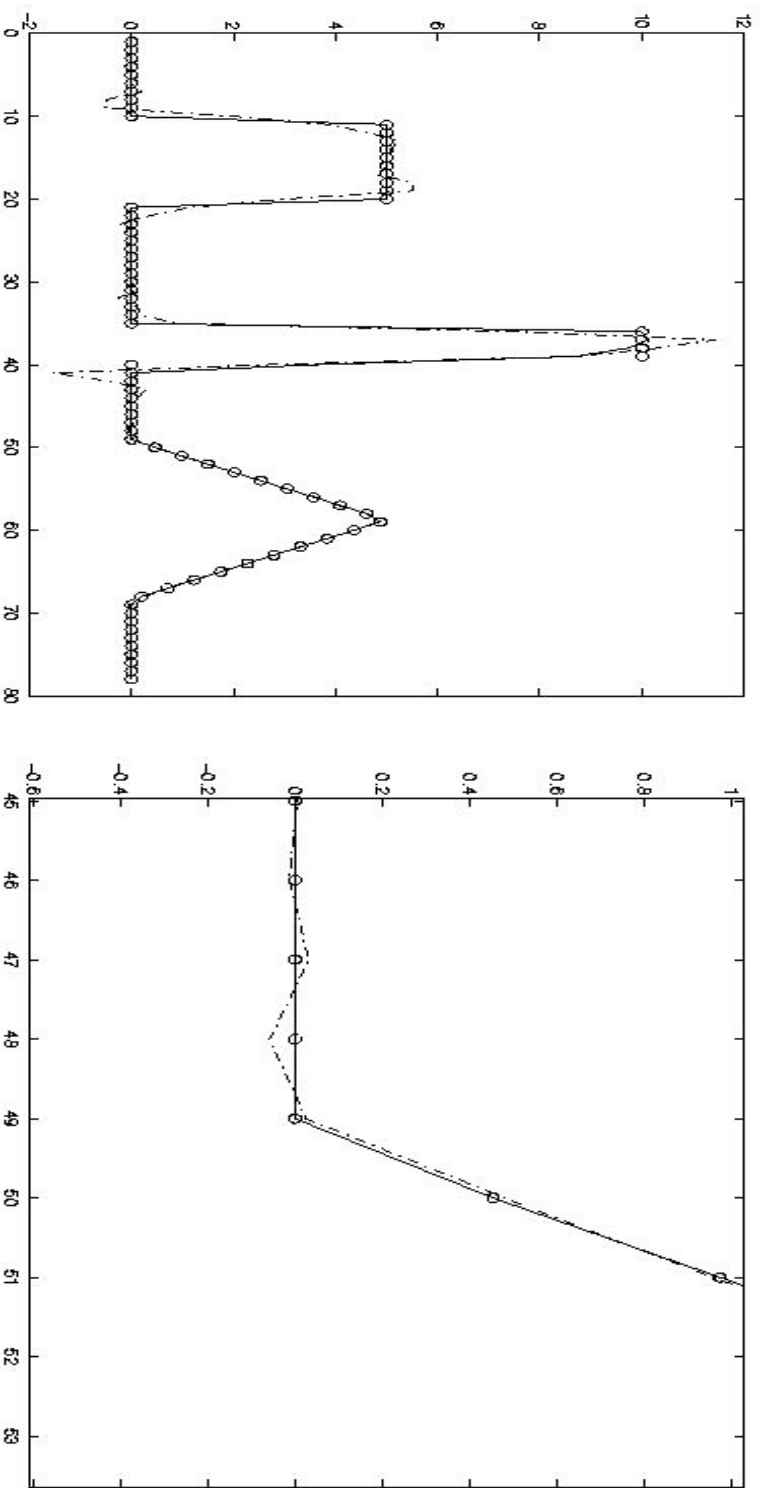
• Stable

• Can use other extrapolation schemes

• Apply to other (non-orthogonal) wavelets

• 2-D by tensor products

Tests on DSP



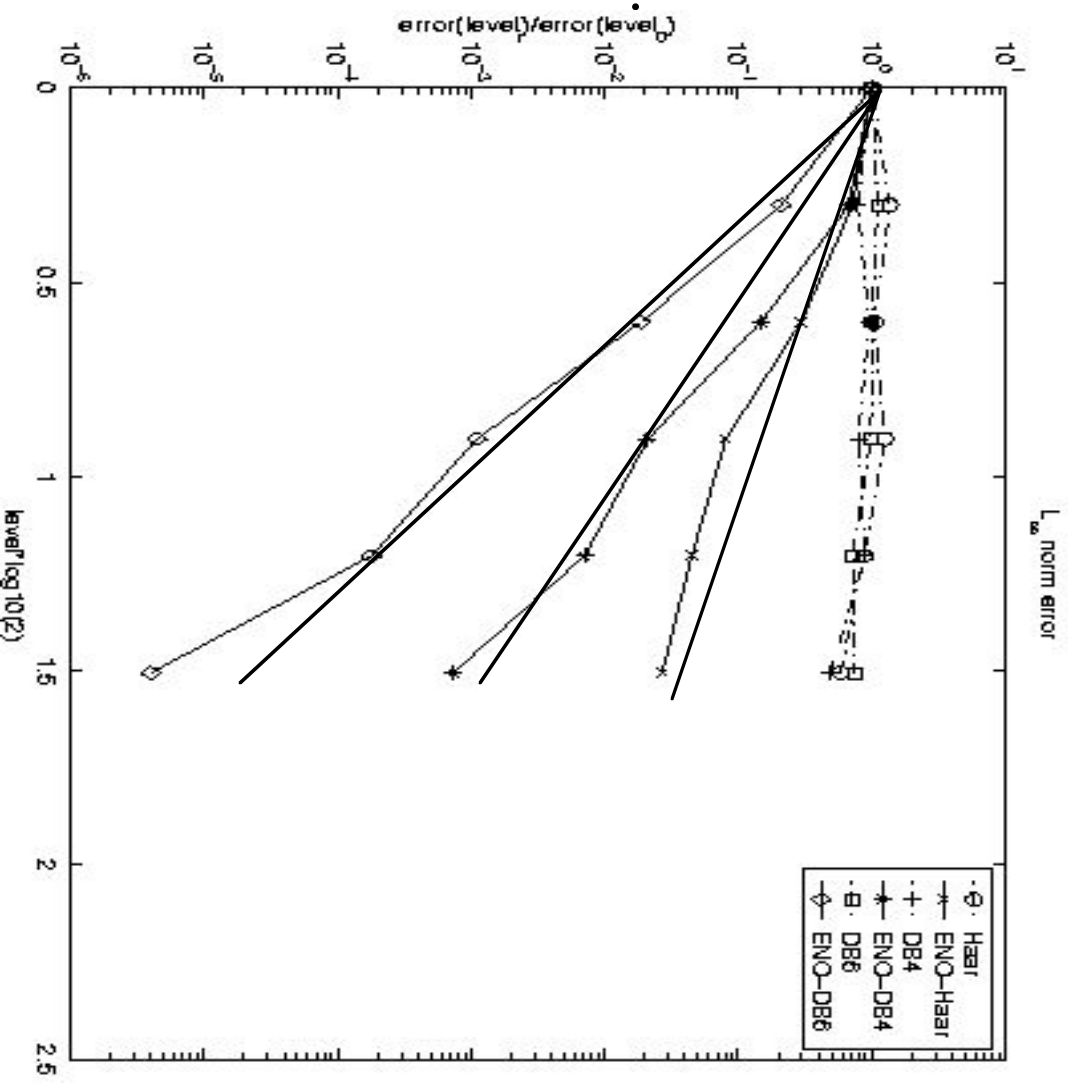
The level-1 ENO-DB6 v.s. DB6 at places where

- ∅DSP satisfied (left bump): exactly.
- ∅DSP invalid (middle bump): error comparable.
- ∅ump in derivatives (right corners): exactly.

Order of Approximation

Order in L^∞

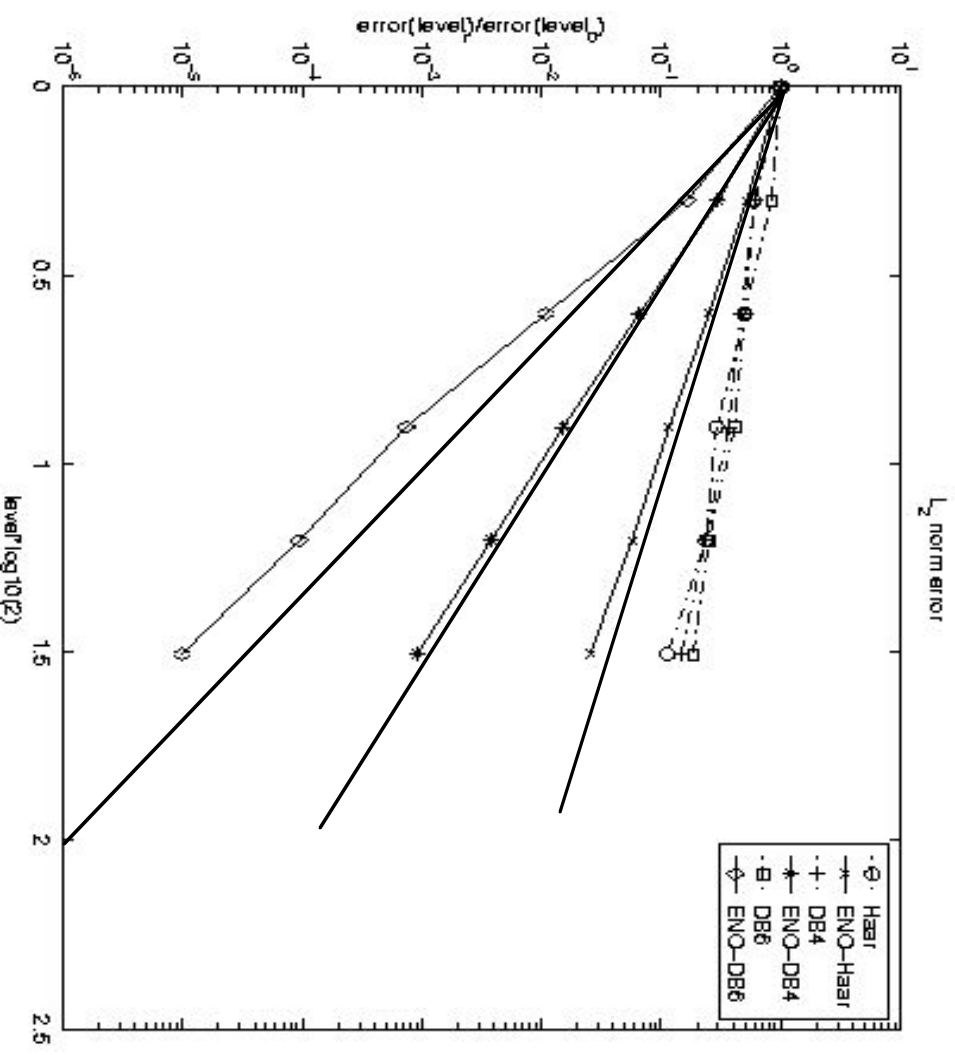
- ⚡ All standard: No order.
- ⚡ ENO-Haar: first.
- ⚡ ENO-DB4: second.
- ⚡ ENO-DB6: third.



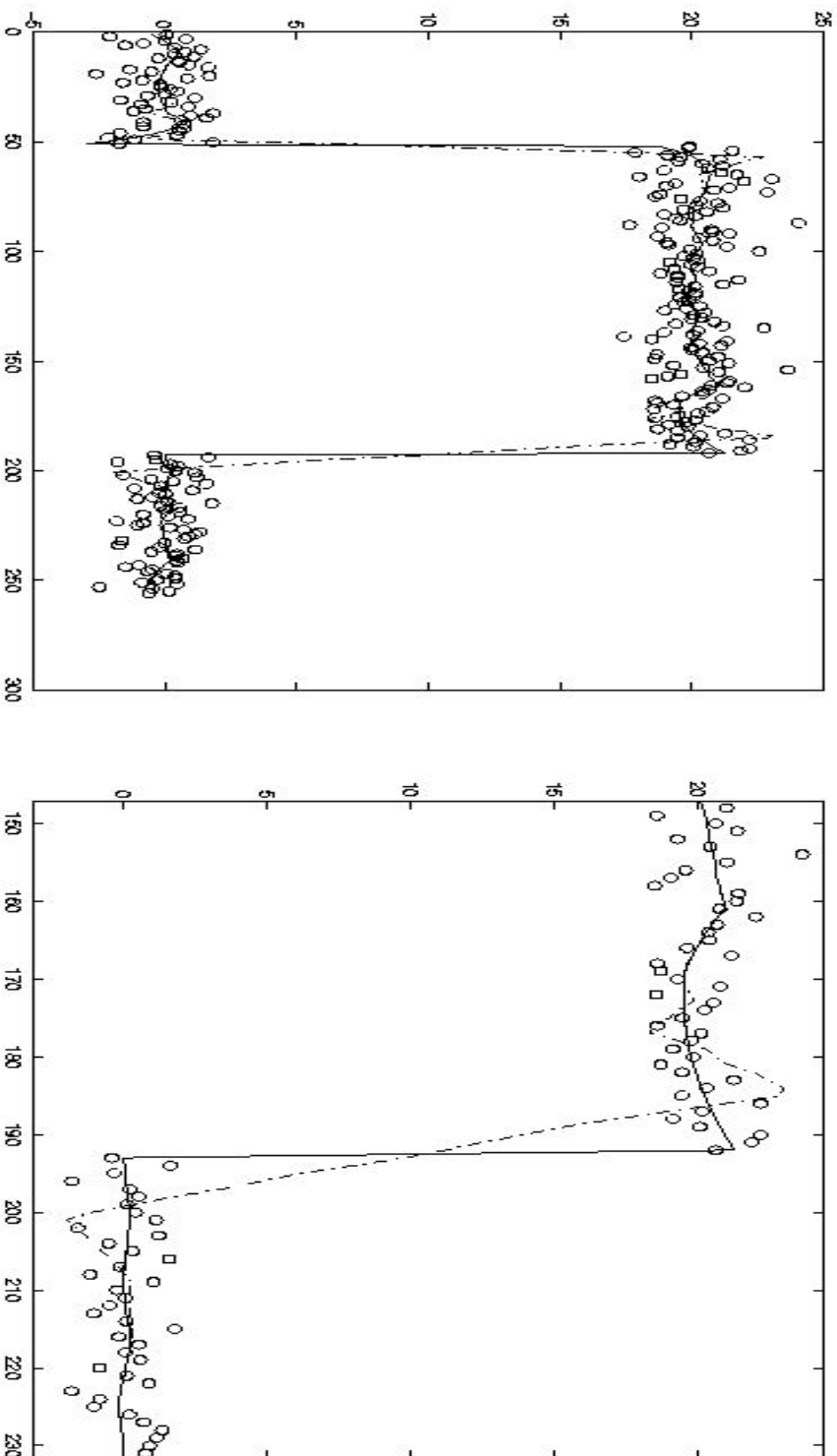
Order of Approximation ...

Order in L^2

- ⚡ All standard: No order
- ⚡ ENO-Haar: first
- ⚡ ENO-DB4: second
- ⚡ ENO-DB6: third

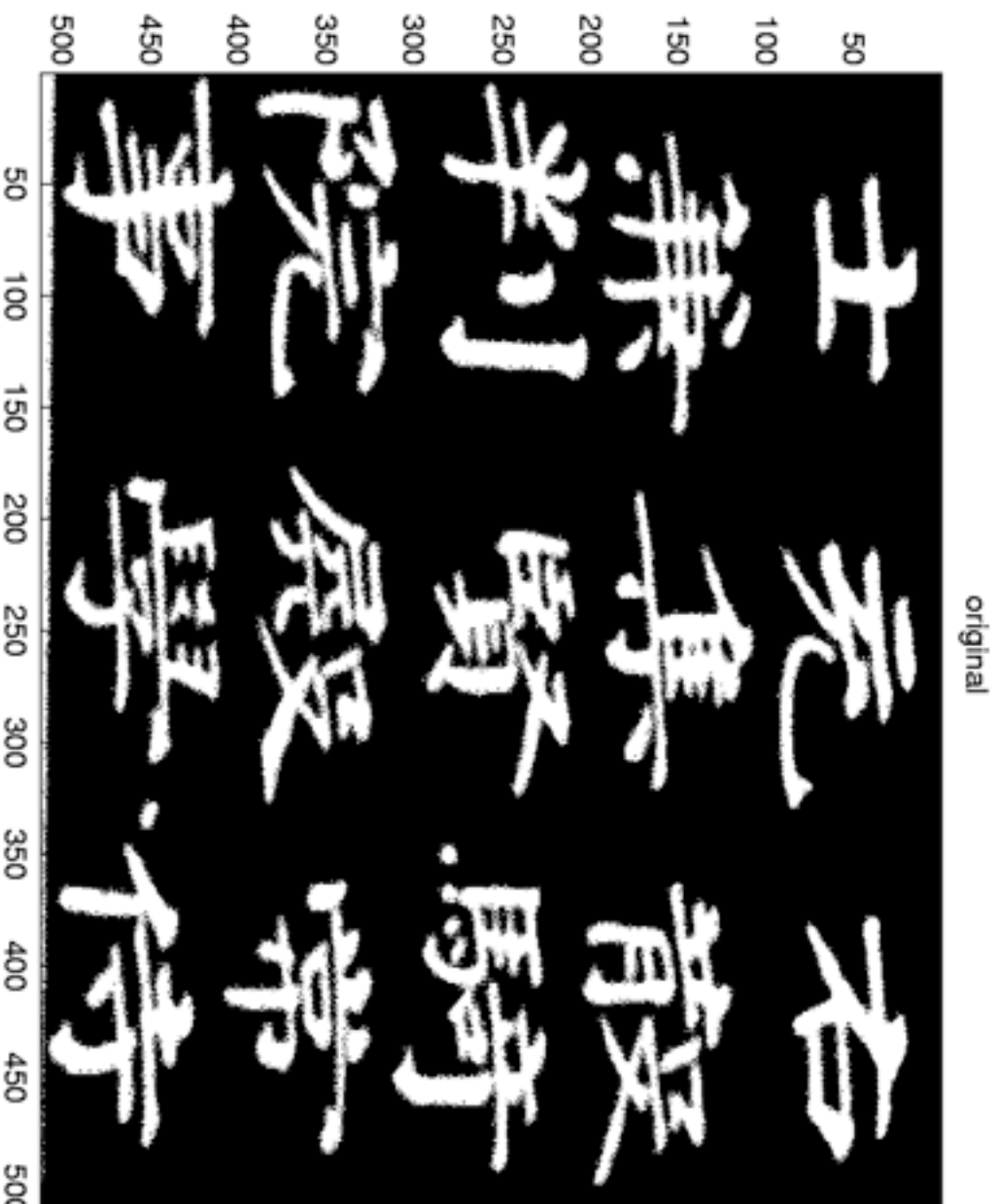


Noisy Data



3-level ENO-DB6 v.s. DB6

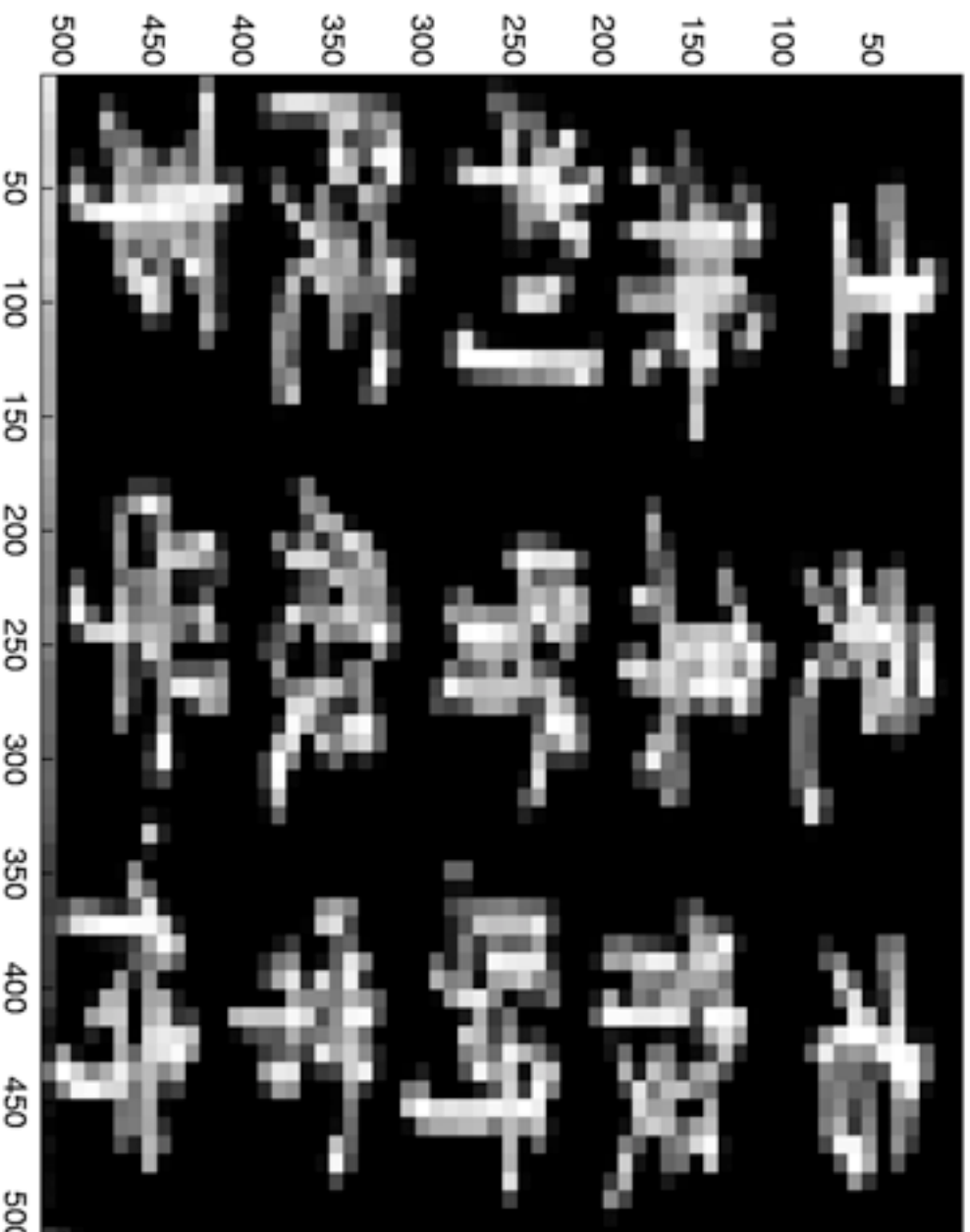
2-D Example



Original 2-D Function

Haar

Haar, level=3, keep 64x64 coefficients



3-level Haar, edges and interior are fuzzy

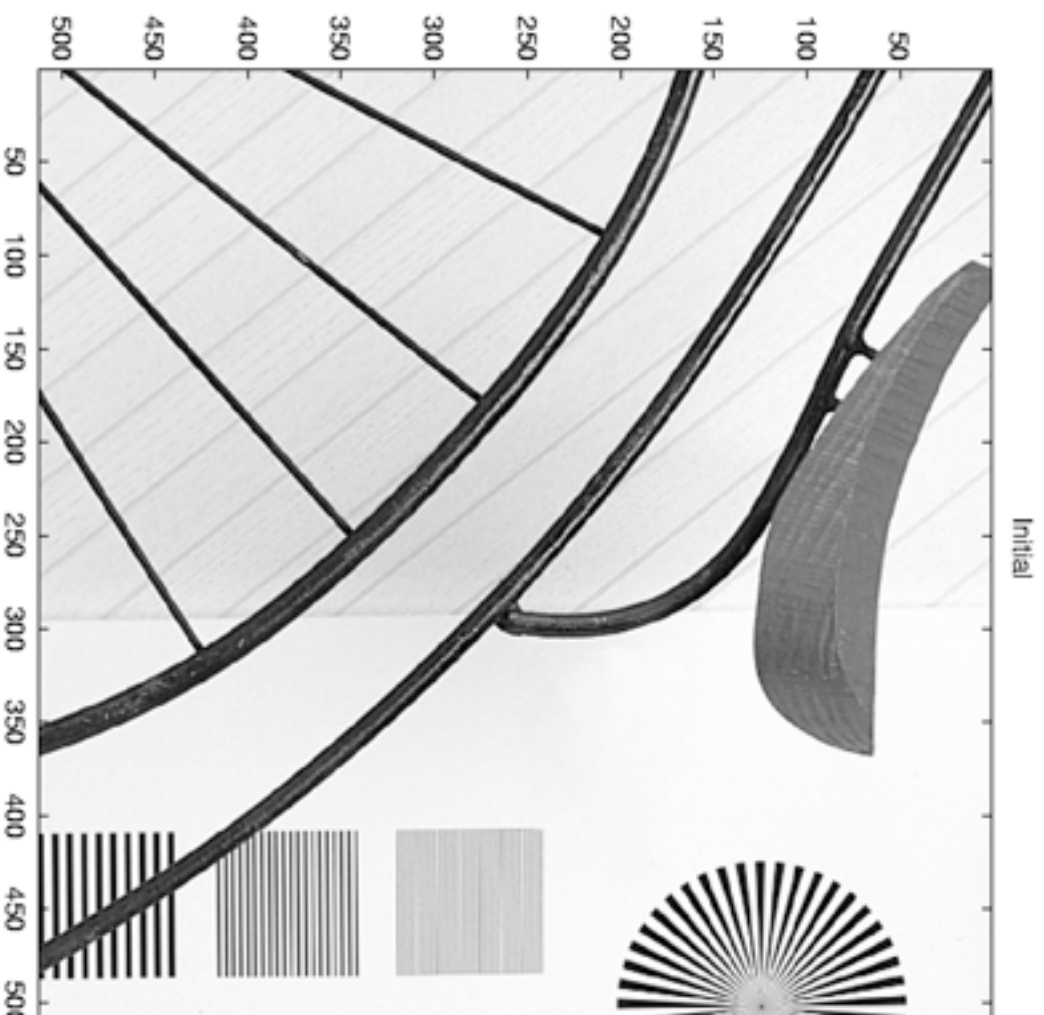
ENO-Haar

ENO-Haar, level=3, keep 64x64 coefficients



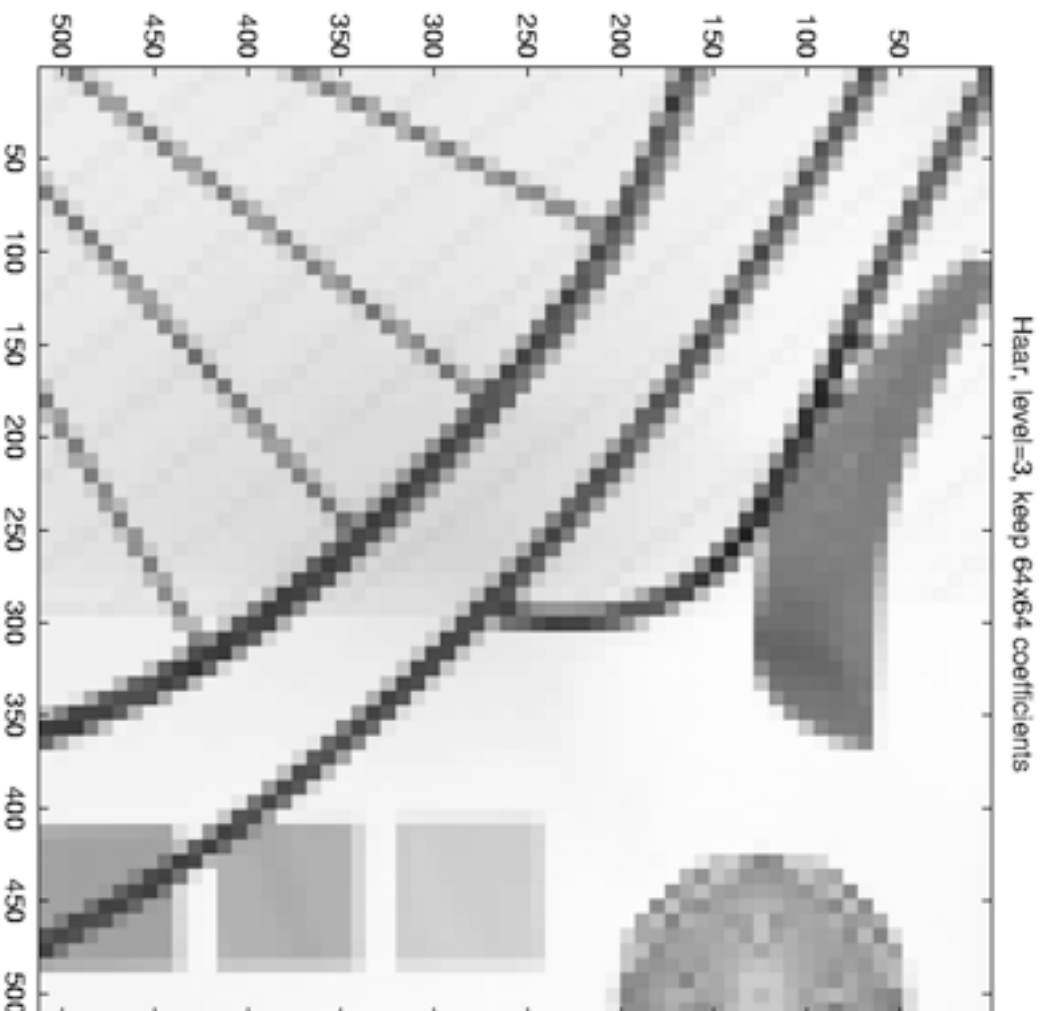
3-level ENO-Haar, Edges and interior are clearer

2-D EXample ...



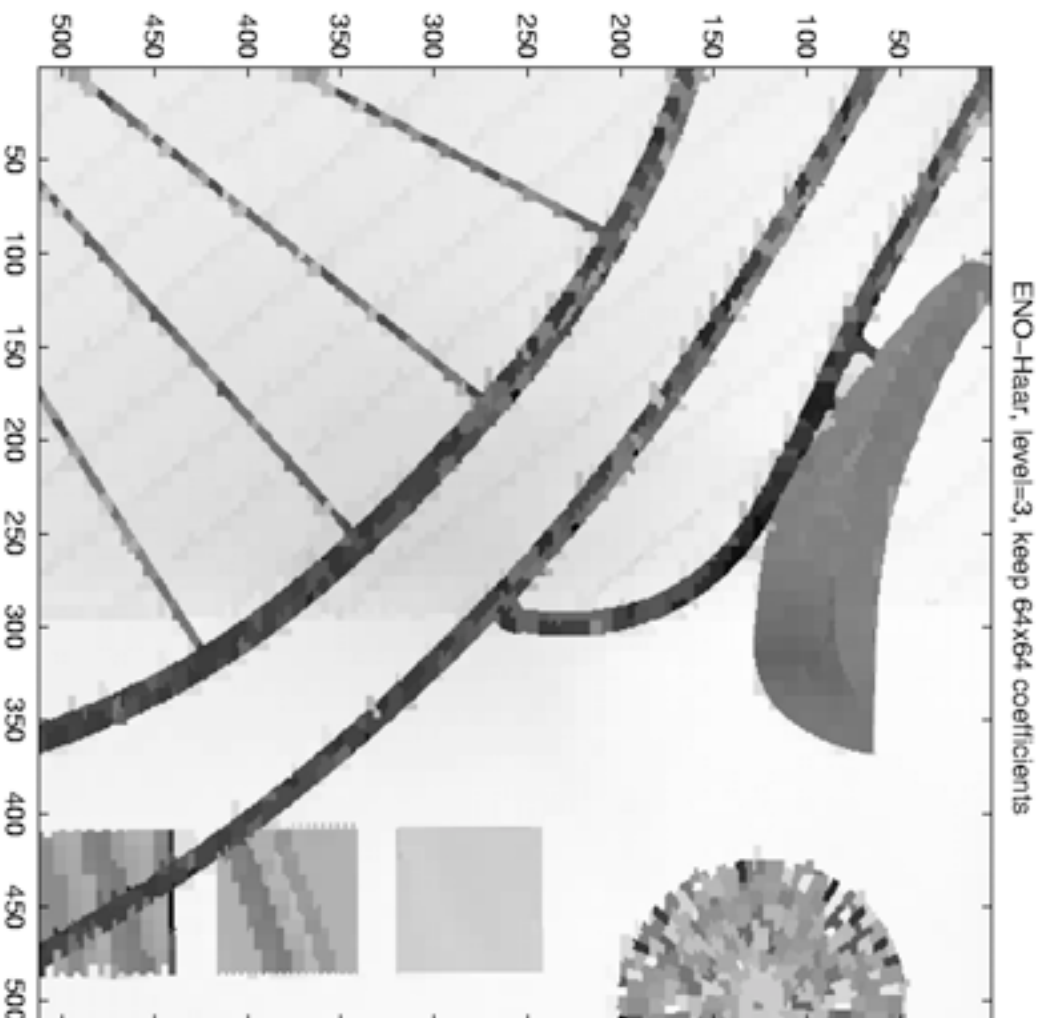
Original 2-D Function

Haar



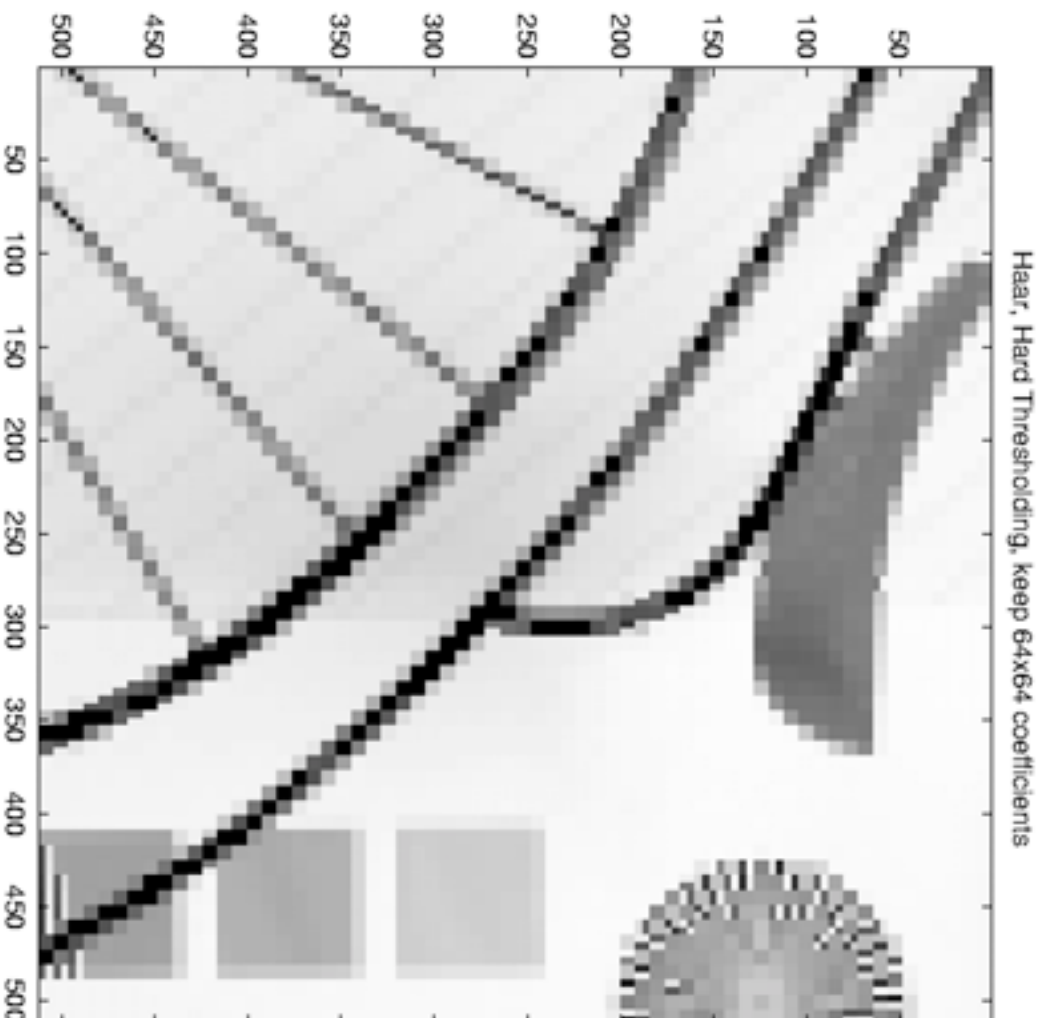
3-level Haar, keep 64x64 coefficients

ENO-Haar



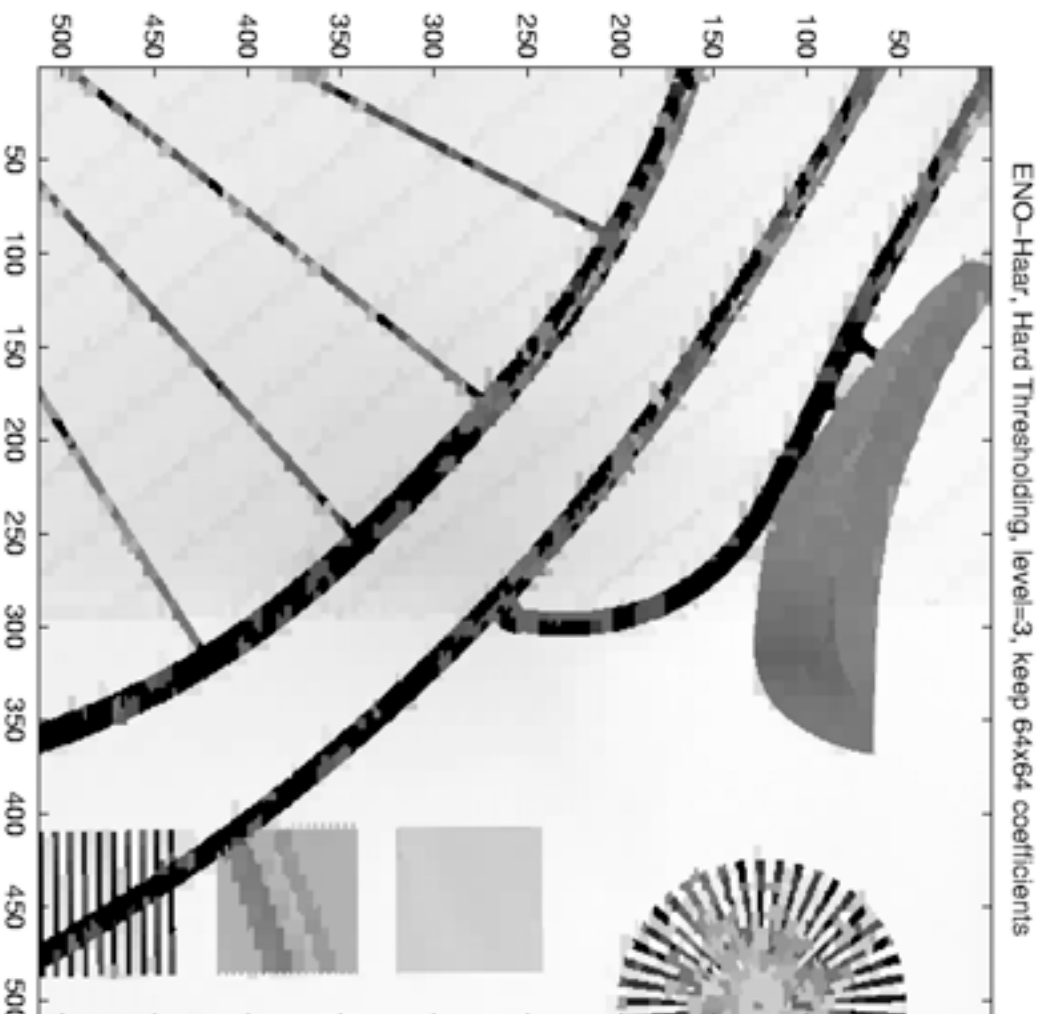
3-level ENO-Haar, keep 64x64 coefficients

Haar, Hard Thresholding



3-level Haar, Hard thresholding, keep 64x64 coef.

ENO-Haar, Hard Thresholding

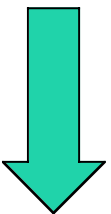


3-level ENO-Haar, Hard thresholding, keep 64x64 coef.

Outline

§ Introduction & Motivations

§ ENO-Wavelet Transforms



§ Application in Image Compression

§ Total Variation (TV) Model for
Wavelet Thresholding

§ Conclusion

Application in Image Compression

✂Represent images by fewer wavelet or ENO-wavelet coefficients

✂Is this sufficient for the efficiency of image compression?

✂Answer is NO

✂Reason: there are more components, not only transforms, in a compression system, and they have to be considered too.

Components of Image Compression Systems



¥ Transform: redundancy removal,
e.g. DCT, Wavelets

¥ Quantizer: entropy (information) reduction,
e.g. Scalar quantizer: real number → integers

¥ Coder: lossless coding
e.g. Huffman, LZW, arithmetic coding

Task

⌘ Efficiency in storage

Rate (bits/pixel) as low as possible.

⌘ Accuracy in representations

Distortion (error: PSNR) as small as possible.

⌘ Optimize rate-distortion trade-off on a range of rates specified by the users.

Multi-resolution (MR) Codes

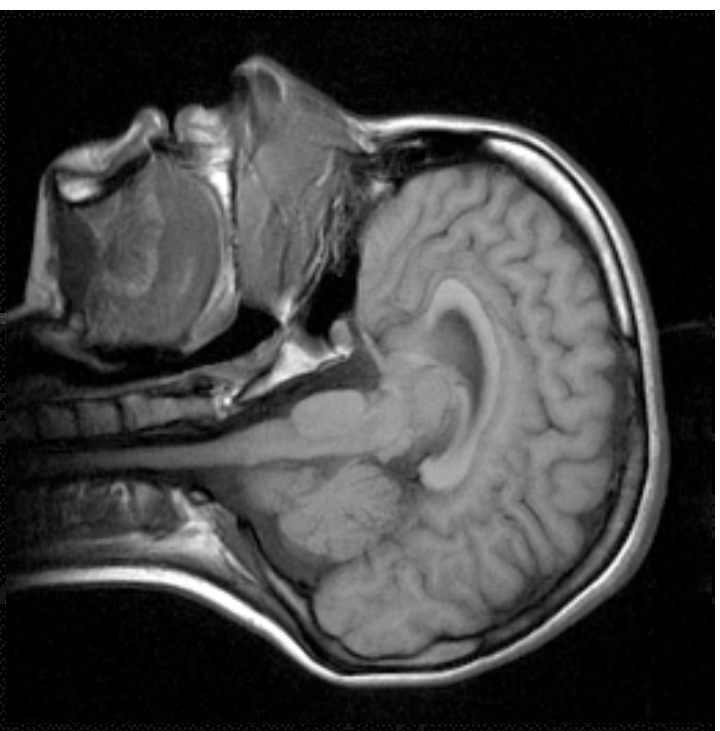
MR code: a single compression system to reproduce at a variety of rates and resolutions.

Also called progressive transmission, embedded or successive refinement codes.

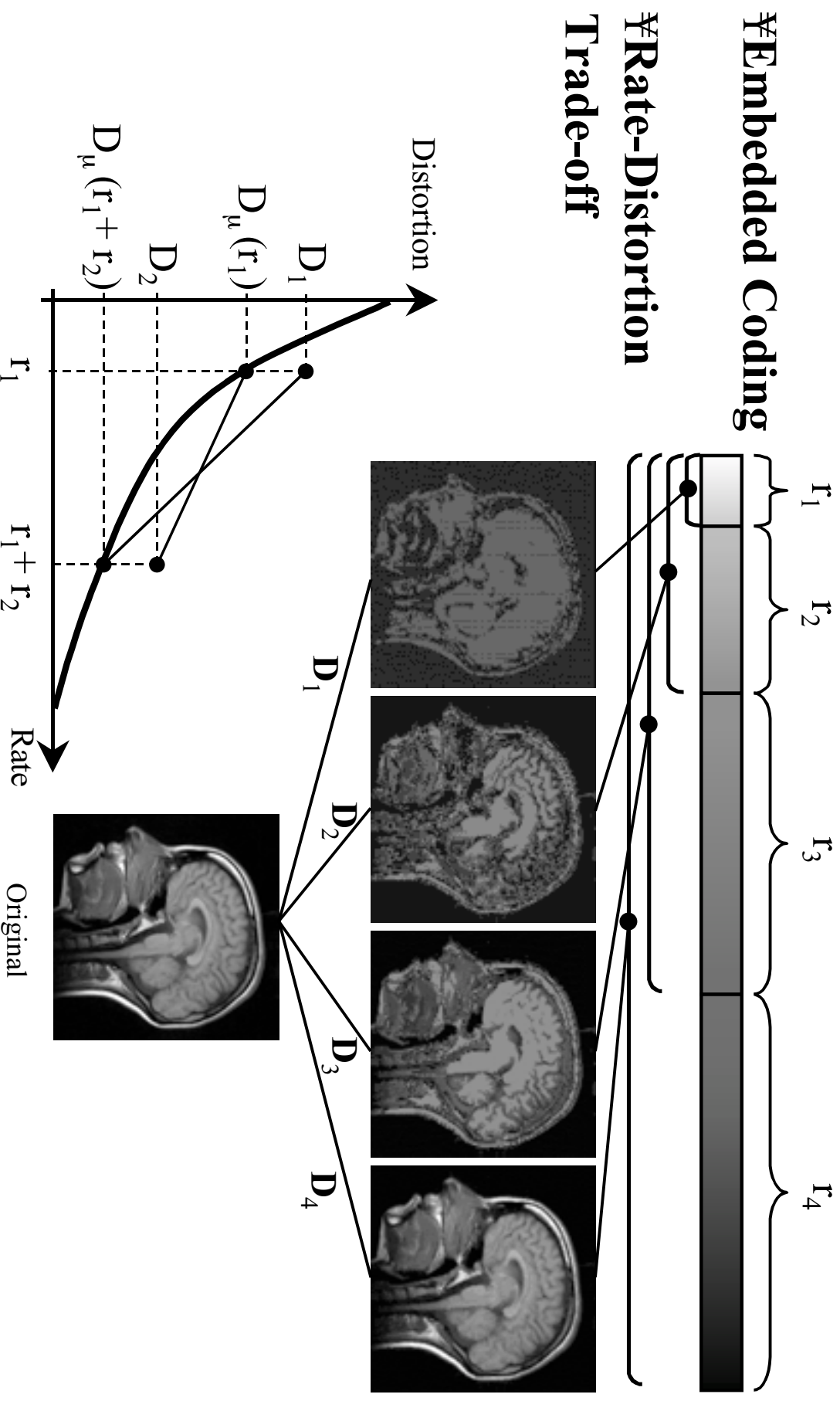
Low-resolution are embedded in higher-resolution of the same data set.

Applications: a single source must be accessible to different users or at different rates that varies, e.g. images on internet.

Multi-resolution (MR) Codes



Multi-resolution (MR) Codes



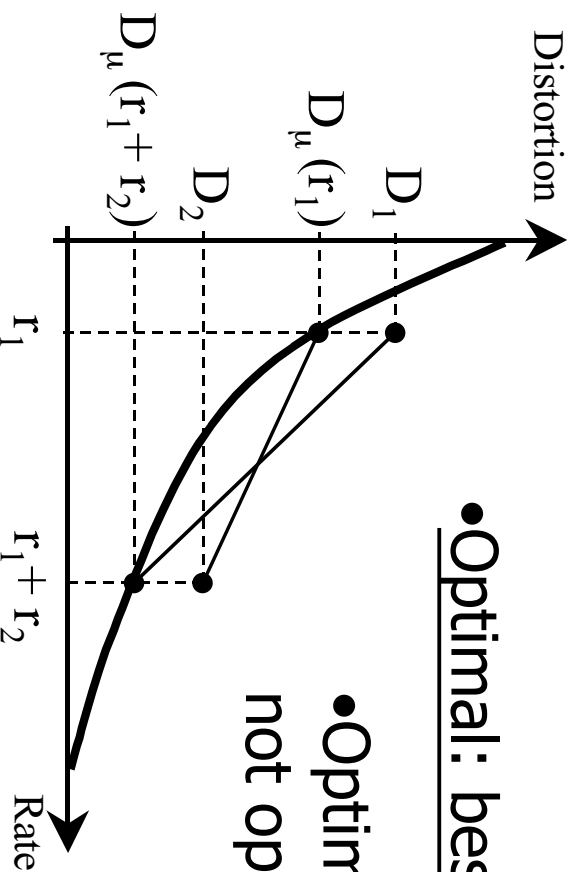
Why MR Codes?

• Applications: a single source must be accessible to different users or at different rates that varies, e.g. images on internet.

• Different demands at different rates

Rate-Distortion Trade-off

- A lower bound on the rate-distortion curves (Shannon).
- One can design codes to achieve the bound arbitrarily close at a given rate.



- Optimal: best rate-distortion trade-off.

• Optimal code at one rate is not optimal at a different rate

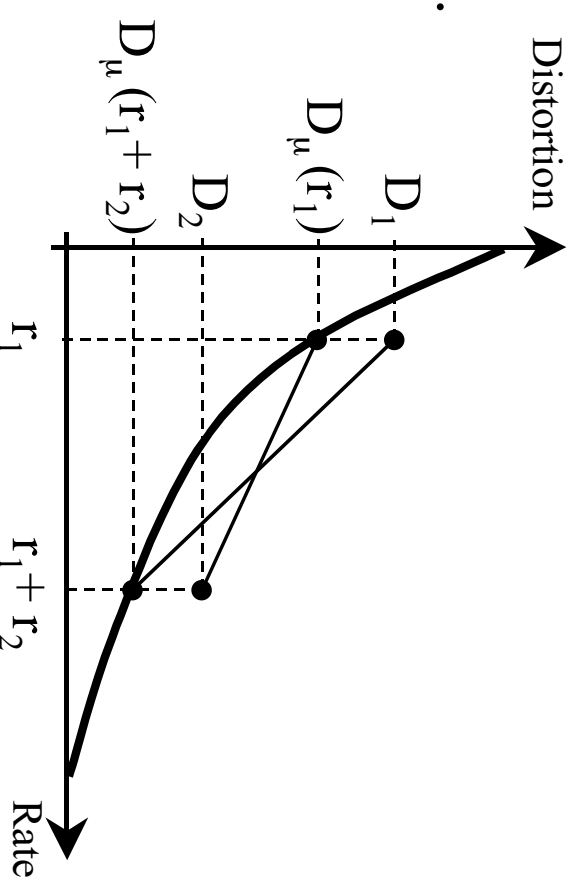
≠ Optimize according to the rate priorities

Multi-resolution (MR) Codes

⚡ Creating an L -resolution code with optimal performance at ***ONE*** of its L resolutions: **Not Difficult**

⚡ Constructing an L -resolution code with optimal performance at ***MORE THAN ONE*** of its L resolutions **may not be possible**

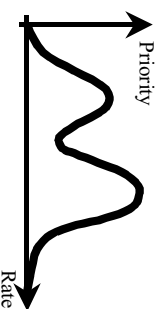
⚡ Priorities may be necessary.



Rate-Distortion Optimization

✧ MR Lagrangian measure $J = \sum_{\ell=1}^L [\alpha_{\ell} D_{\ell} + \beta_{\ell} R_{\ell}]$

✧ Priorities $\{\alpha_{\ell}, \beta_{\ell}\}$



✧ Minimize $J \rightarrow$ optimal performance

✧ Trade-off of ENO-Wavelet: Storage of locations of discontinuities v.s. Relative savings of smaller high freq.

State of the art compression: GTW

‡ Group Testing on Wavelet (GTW) coefficients is a recent (Hong & Ladner 2000) *lossy* coding technique which can efficiently represent few significant elements in a large pool of coefficients.

‡ Zero-tree type of coding algorithm implemented in bit-plane fashion: instead of deciding whether to keep a whole coefficient, the decision is made on every bit of the coefficient.

‡ Key trade-off: for every-one bit of a coefficient, storing it as 1 will decrease the distortion, but increase the rate.

State of the art compression: GTW

#Hong & Ladner, 2000

#Zero-tree type of bit-plane coding

#Use Group Testing (GT) to wavelet coefficients

#GT: an efficient way to identify few significant elements in a large pool

Optimization of GTW

#Dugatkin, Zhou, Chan and Effros (2002)

#Optimize the Lagrangian rate-distortion trade-off performance: $J = \sum_{\ell=1}^L [\alpha_{\ell} D_{\ell} + \beta_{\ell} R_{\ell}]$, α, β are weights.

#Incorporate ENO-Wavelet Coefficient in the optimization procedure.

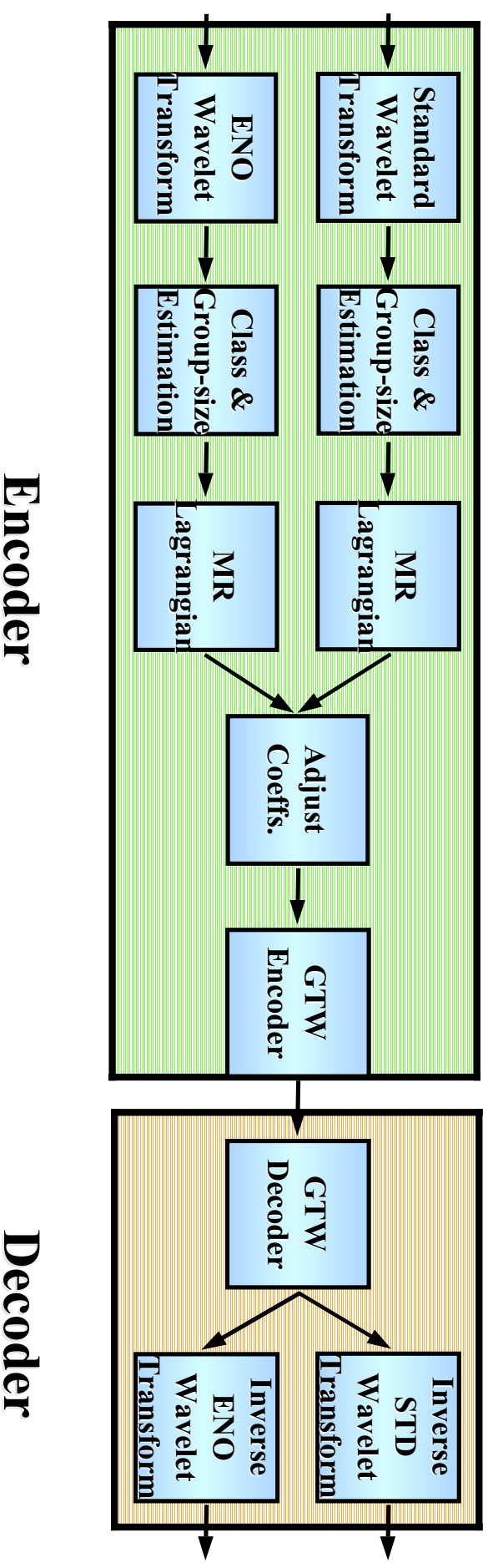
#Trade-off of ENO-Wavelet: Storage of locations of discontinuities v.s. Relative savings of smaller high freq., which is considered in the Lagrangian

Optimization of GTW

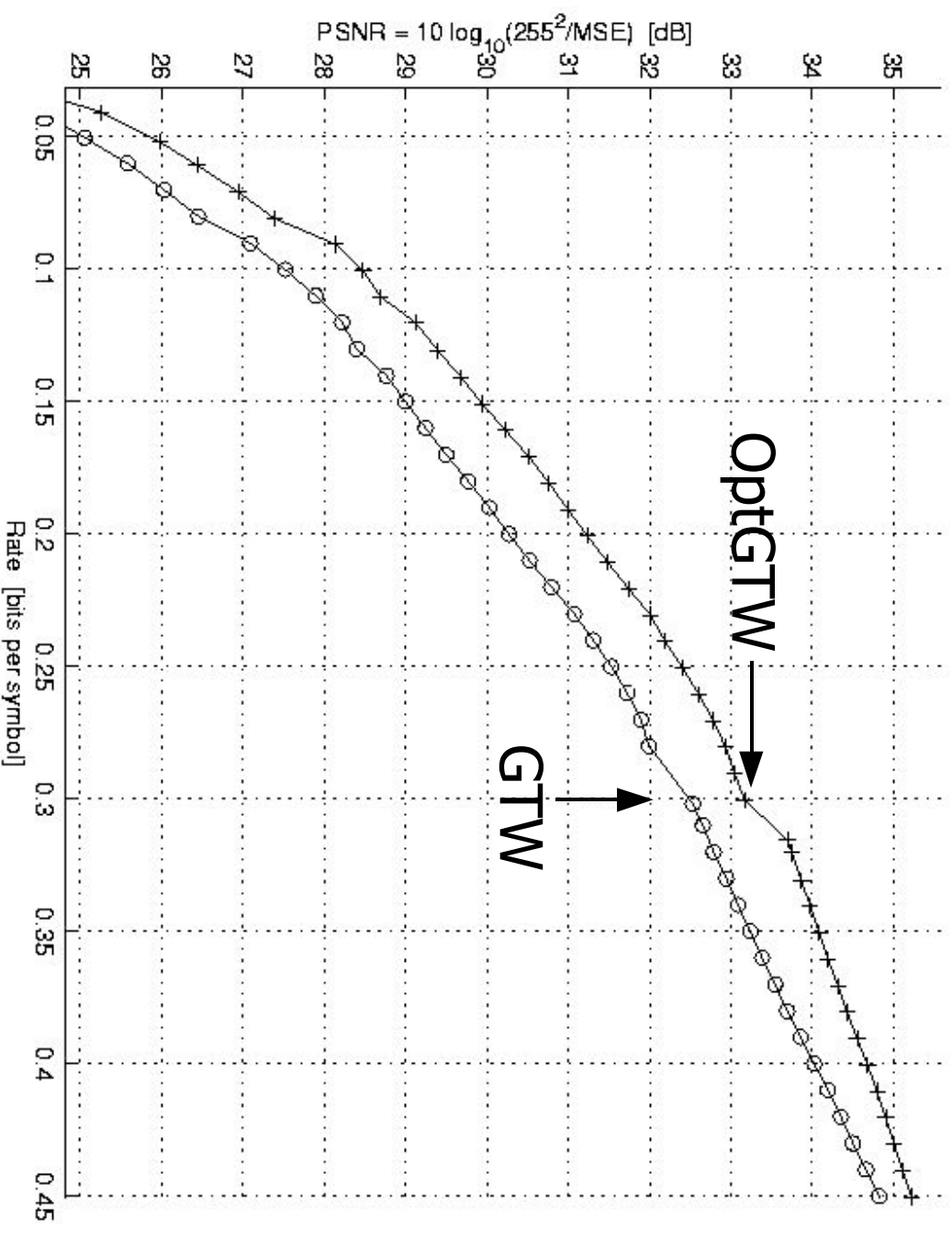
✂Optimize the Lagrangian rate-distortion trade-off performance at each bit-plane

✂Incorporate ENO-Wavelet Coefficient in the optimization procedure.

Algorithm



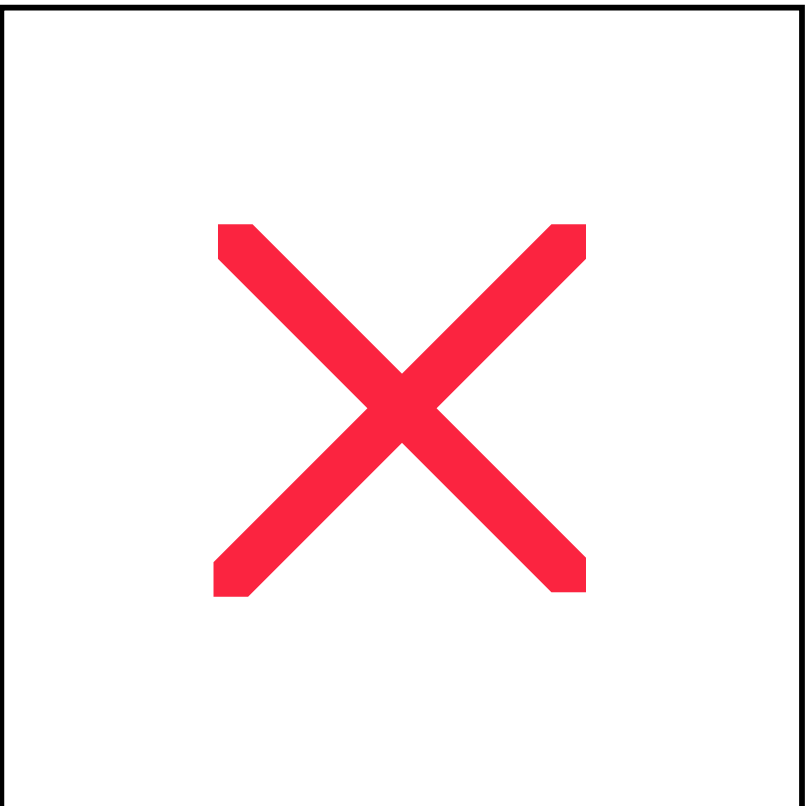
PSNR vs. Rate results



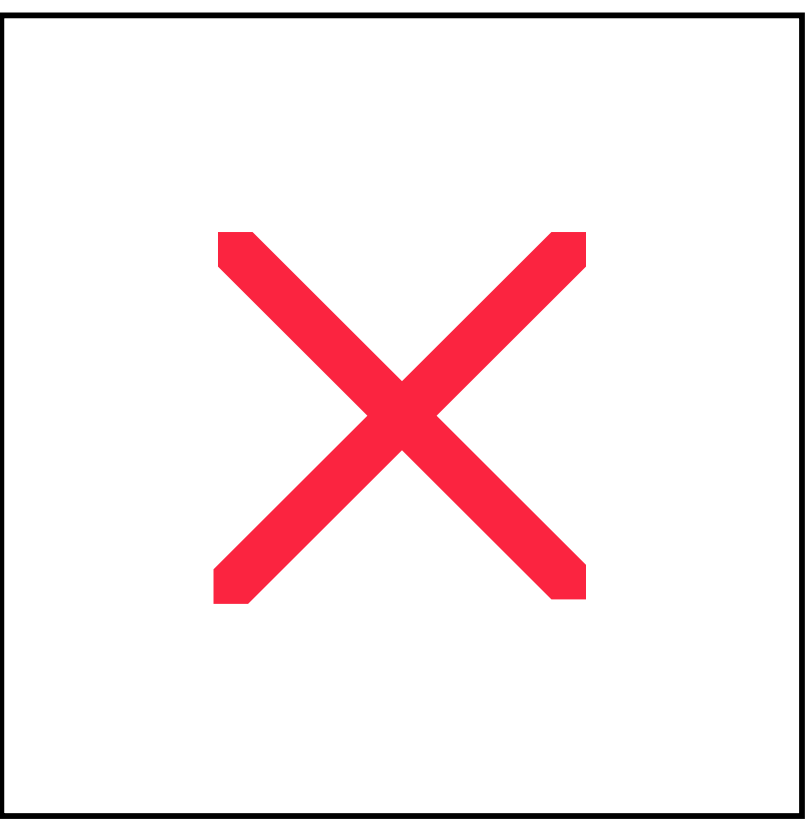
Save over 1.0dB

Visual quality

Standard GTW



New OPT-GTW with ENO



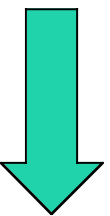
cameraman reconstructed image at $R=0.1$ bpp, better
edge reconstruction

Outline

‡ Introduction & Motivations

‡ ENO-Wavelet Transforms

‡ Application in Image Compression



‡ Total Variation (TV) Model for
Wavelet Thresholding

‡ Conclusion

Topic 2

TV models for wavelet thresholding and its application in image compression and denoising

TV Image Processing

Great success of TV in image processing, (Rudin, Osher, Fatemi): smooth oscillations but retain sharp edges.

Many people work on it: Chan, Osher's group, Vogel, Santosa, Dodson, Plemmons, Chambolle, Lions

Applications in image processing: Denoising, Deblurring, Segmentation, Color images, Image on manifolds, Digital TV filters

Motivations for Topic 2

Great success of TV in image processing, (Rudin, Osher, Fatemi): smooth out oscillations but retain sharp edges.

Denoising (Chan, Osher's group, Vogel ...)

Blind deconvolution (Chan-Wong)

Color TV: (Chan-Blomgren)

Digital TV filters: (Chan-Shen)

Segmentation: (Chan-Vese)

Images on manifolds: (Osher-Cheng)

TV in Image Processing

Chambolle, DeVore, Lee and Lucier:
min. in Besov by wavelets

TV denoising + Wavelet Thresholding:
better ratio or quality (Chan-Zhou, 1998)

Oscillations generated by thresholding
increase TV norm

TV in Wavelet Thresholding

- ✚ Chan & Zhou (2000): TV optimized wavelet coefficients in image compression and denoising.
- ✚ Durand & Froment (2001): fixed the retained wavelet coefficients in hard thresholding and adjust others to minimize the TV norm to erase the oscillations.
- ✚ Candes (2001): TV post processing for curvelet thresholding

General TV Model

$$\min_{\beta_{j,k}, (j,k) \in I} \lambda \int |\nabla u(\beta, x)| dx + \|u - z\|_2^2$$

$$\text{S.T.} \quad |I| = m$$

Where

$$u = \sum_{j,k} \beta_{j,k} \varphi_{j,k}(x)$$

$$z = \sum_{j,k} \alpha_{j,k} \varphi_{j,k}(x) \quad \text{— Observed image}$$

$$m \quad \text{— Given integer}$$

General TV Model

⌘ Nonlinear integer optimization

⌘ Difficulties: Integer constraint, too many local solutions, nonlinear equations.

⌘ Selection of λ : L-curve, training images

General TV Model

$\lambda \longrightarrow 0$, Standard Thresholding

$\lambda \longrightarrow \infty$, constants

λ : Control the small feature size to preserve (Strang-Chan).

TV Hard Thresh. Model

$$\min_{\beta_{j,k}, (j,k) \in I_H} \lambda \int |\nabla u(\beta, x)| dx + \|u - z\|_2^2$$

Euler-Lagrangian

$$-\lambda \nabla \cdot \left(\frac{\nabla u}{|\nabla u|} \right) \varphi_{j,k} dx + 2(\beta_{j,k} - \alpha_{j,k}) = 0$$
$$(j,k) \in I_H$$

Approximation to Constraint

$$|I| = m$$

Approximate by:

$$\left(\sum_{(j,k)} \log(1 + \beta_{j,k}^2) - m\right)^2 \leq \gamma^2 \quad \text{Olshausen \& Field}$$

$$\left(\sum_{j,k} \left|\beta_{j,k}\right|^p - m\right)^2 \leq \gamma^2, p \rightarrow 0 \quad \text{Donoho(99)}$$

TV Relaxation Models

$$\min_{\beta_{j,k}, (j,k) \in I_H} \lambda \int |\nabla u(\beta, x)| dx + \|u - z\|_2^2 + \tau \left(\sum_{j,k} \log(1 + \beta_{j,k}^2) - m \right)^2$$

OR

$$\min_{\beta_{j,k}, (j,k) \in I_H} \lambda \int |\nabla u(\beta, x)| dx + \|u - z\|_2^2 + \tau \left(\sum_{j,k} |\beta_{j,k}|^p - m \right)^2$$

Euler-Lagrangians

$$-\lambda \nabla \left(\frac{\nabla u}{|\nabla u|} \right) \varphi_{j,k} dx + 2(\beta_{j,k} - \alpha_{j,k}) + 2\tau \left(\sum_{j,k} \log(1 + \beta_{j,k}^2) - m \right) \frac{\beta_{j,k}}{1 + \beta_{j,k}^2} = 0$$

Or

$$-\lambda \nabla \left(\frac{\nabla u}{|\nabla u|} \right) \varphi_{j,k} dx + 2(\beta_{j,k} - \alpha_{j,k}) + 2\tau \left(\sum_{j,k} |\beta_{j,k}|^p - m \right) \frac{\beta_{j,k}}{|\beta_{j,k}|^{2-p}} = 0$$

Numerics

• Time Marching, Fixed-point, Primal-Dual...

• Regularizations to prevent blow-up

• Transform Data between wavelet spaces and physical space.

Fixed-point Iterations

Linearize the nonlinear terms by using previous approximations: e.g.

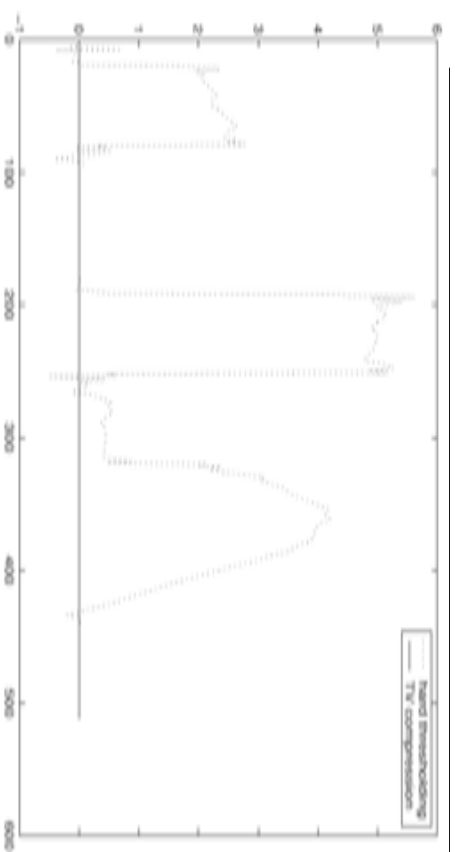
$$-\lambda \int \nabla \cdot \left(\frac{\nabla u^{n+1}}{|\nabla u^n|} \right) \varphi_{j,k} dx + 2(\beta_{j,k}^{n+1} - \alpha_{j,k}) = 0$$

$$(j,k) \in I_H$$

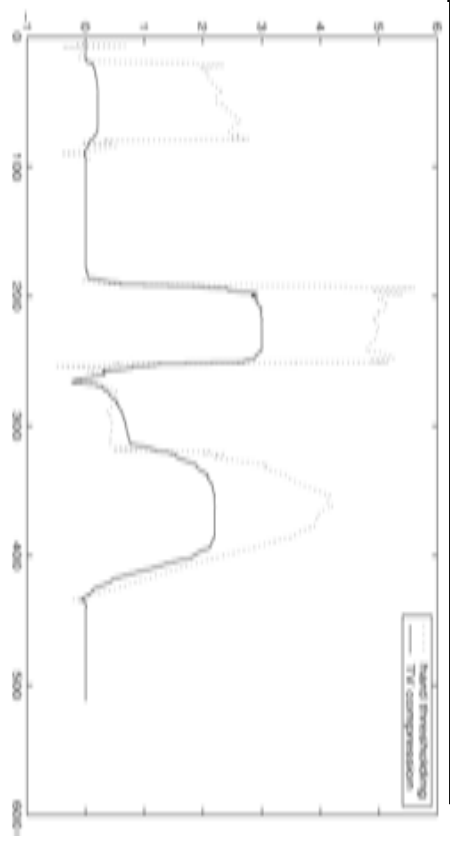
Advantages over TV +Thresh.

- ✱Reduce the oscillations generated by thresholding
- ✱May directly operate on wavelets, easier to combine with comp. schemes.
- ✱Work on smaller space, can be faster potentially.

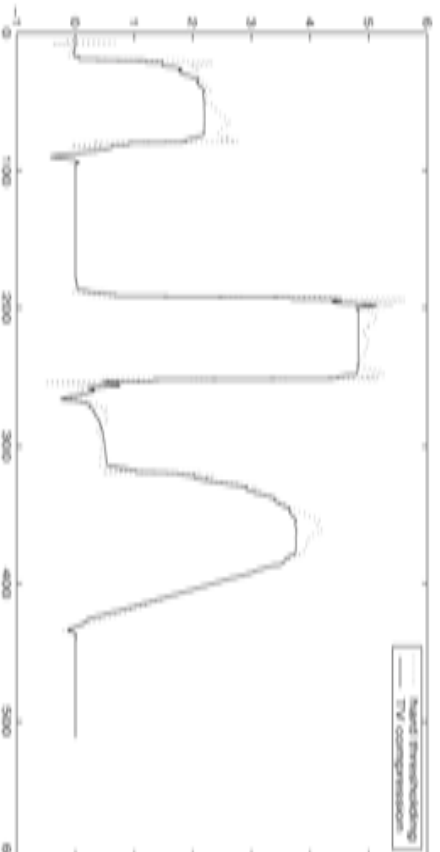
TV Hard Thresholding



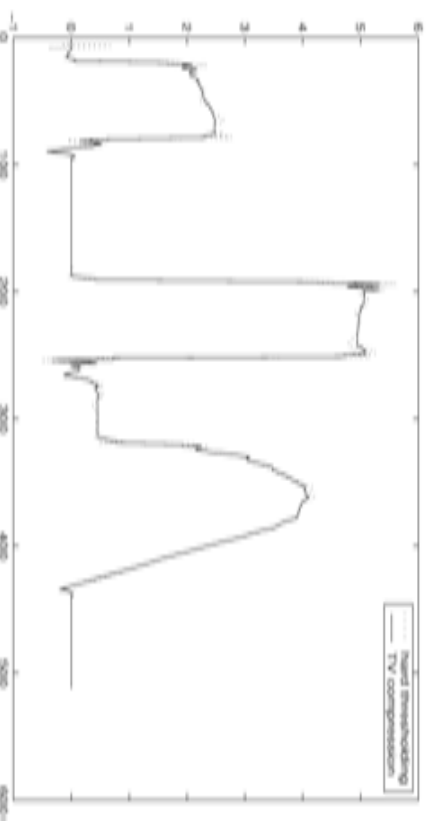
$$\lambda = 1$$



$$\lambda = 0.1$$



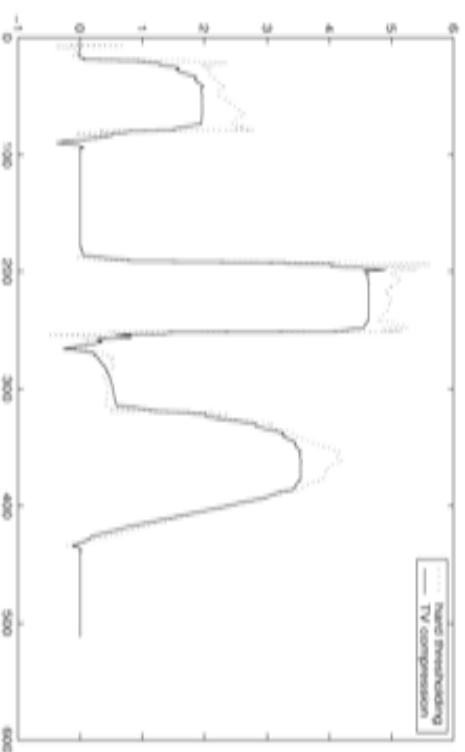
$$\lambda = 0.01$$



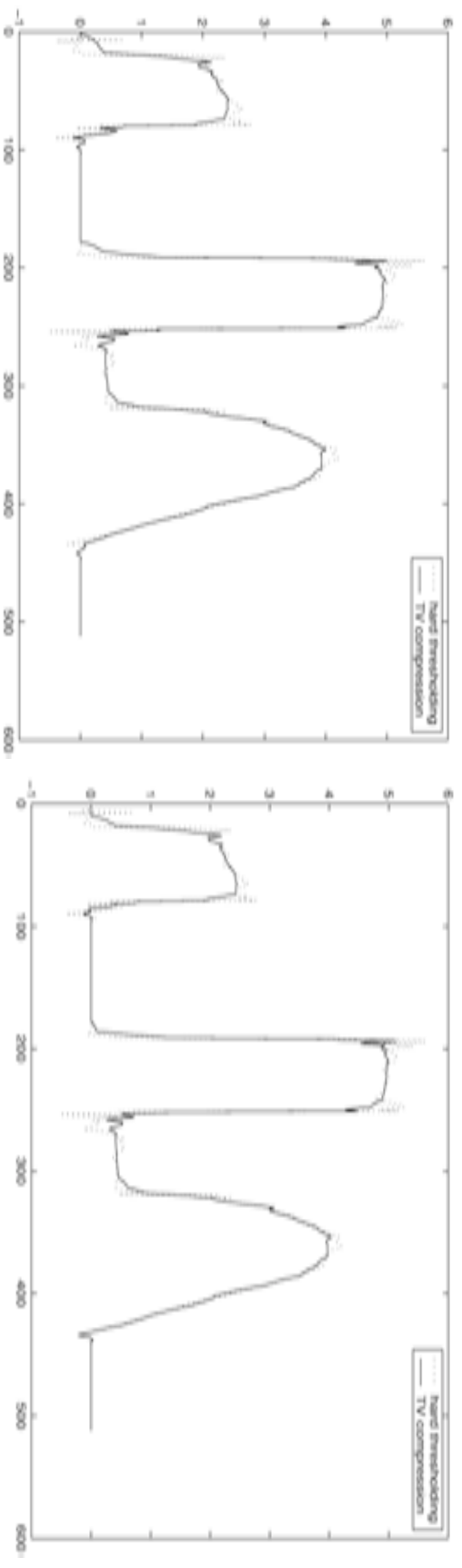
$$\lambda = 0.001$$

4-level DB4, keep 50 largest coefficients

TV Thresholding



Hard Thresh.

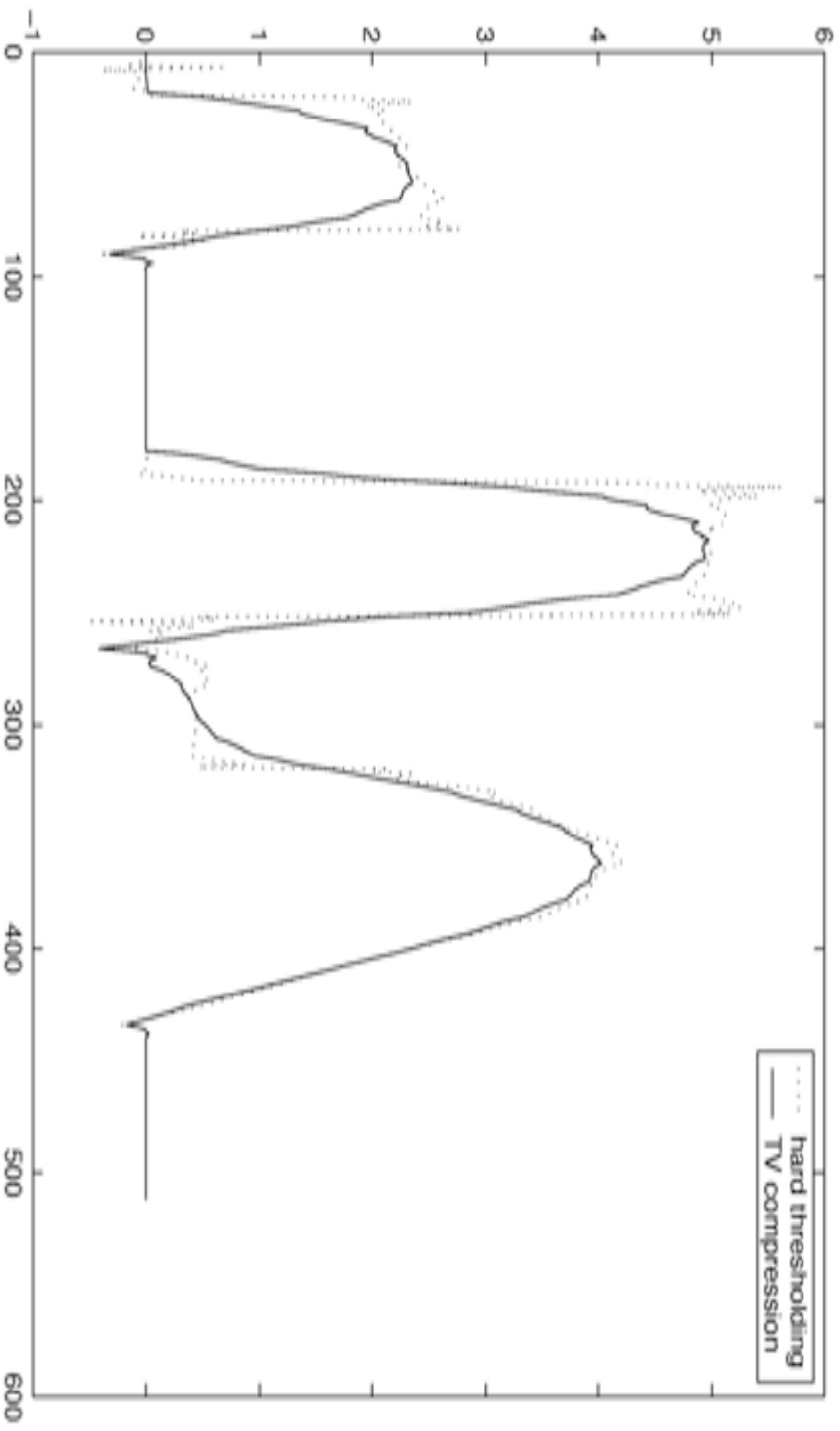


log-function

p-norm

4-level DB4, keep 50 largest coefficients $\lambda = 0.02$

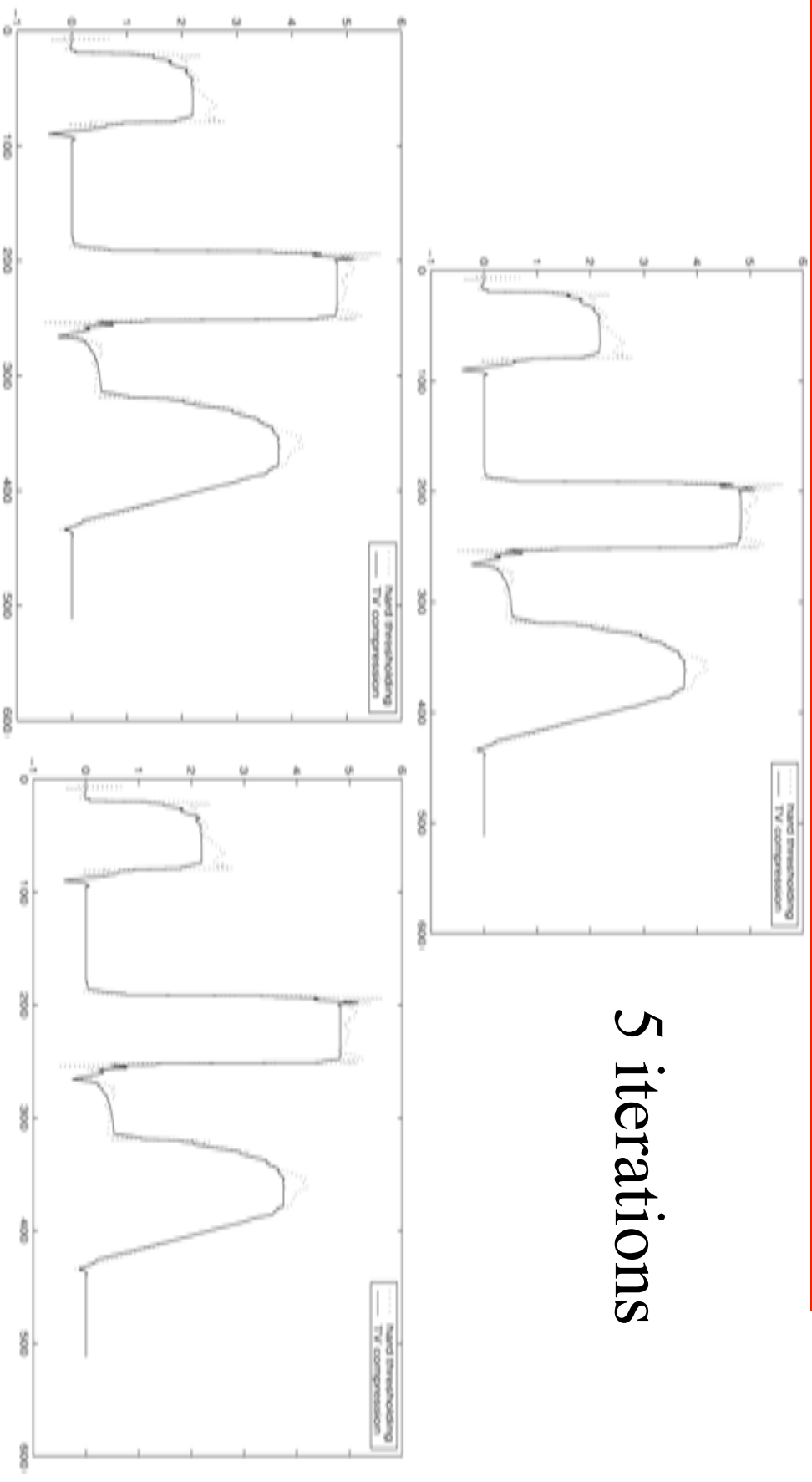
H-1 Regularization



4-level DB4, keep 50 largest coefficients
 $\lambda = 0.0002$

TV Hard Thresholding

5 iterations



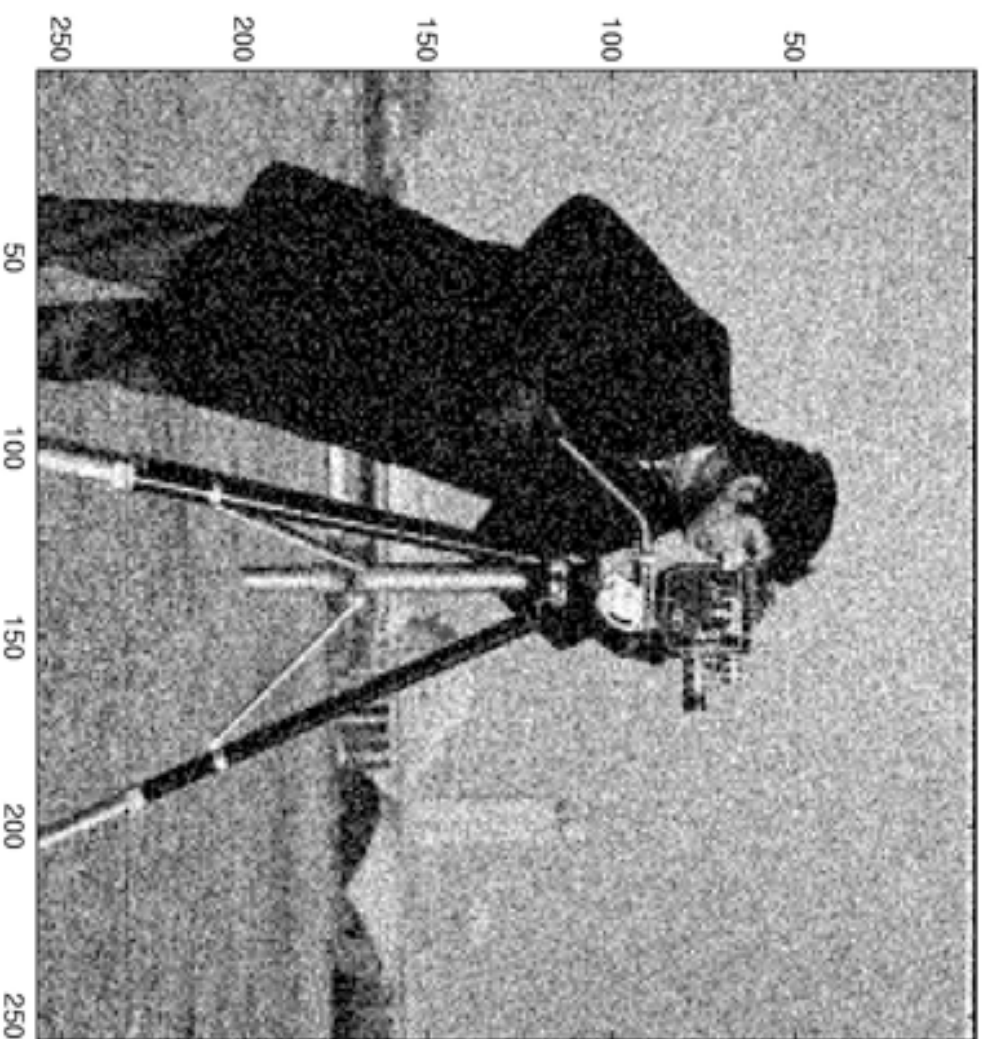
10 iterations

20 iterations

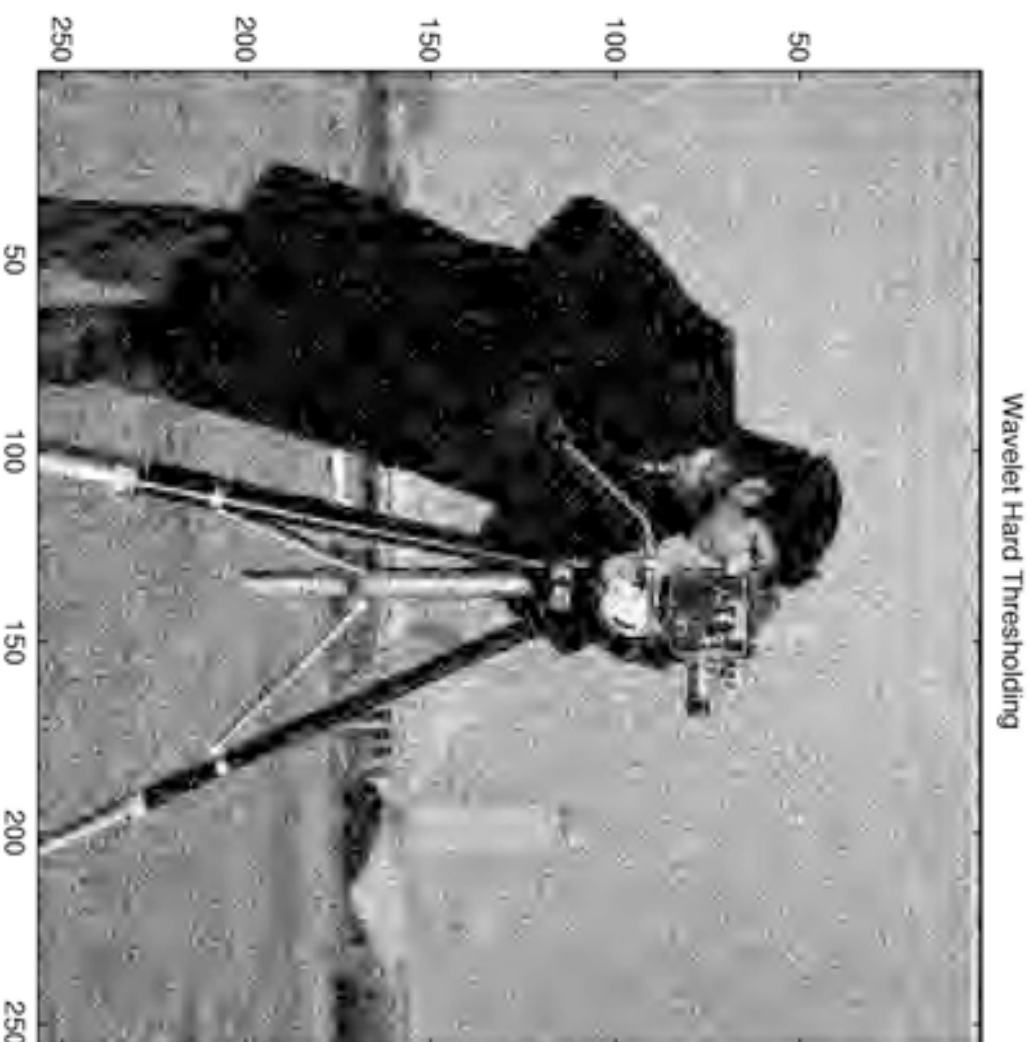
4-level DB4, keep 50 largest coefficients $\lambda = 0.01$

Original Noisy Image

Observed



DB6 Hard Thresholding



4-level DB6, Hard thresholding, keep 64x64 coef.

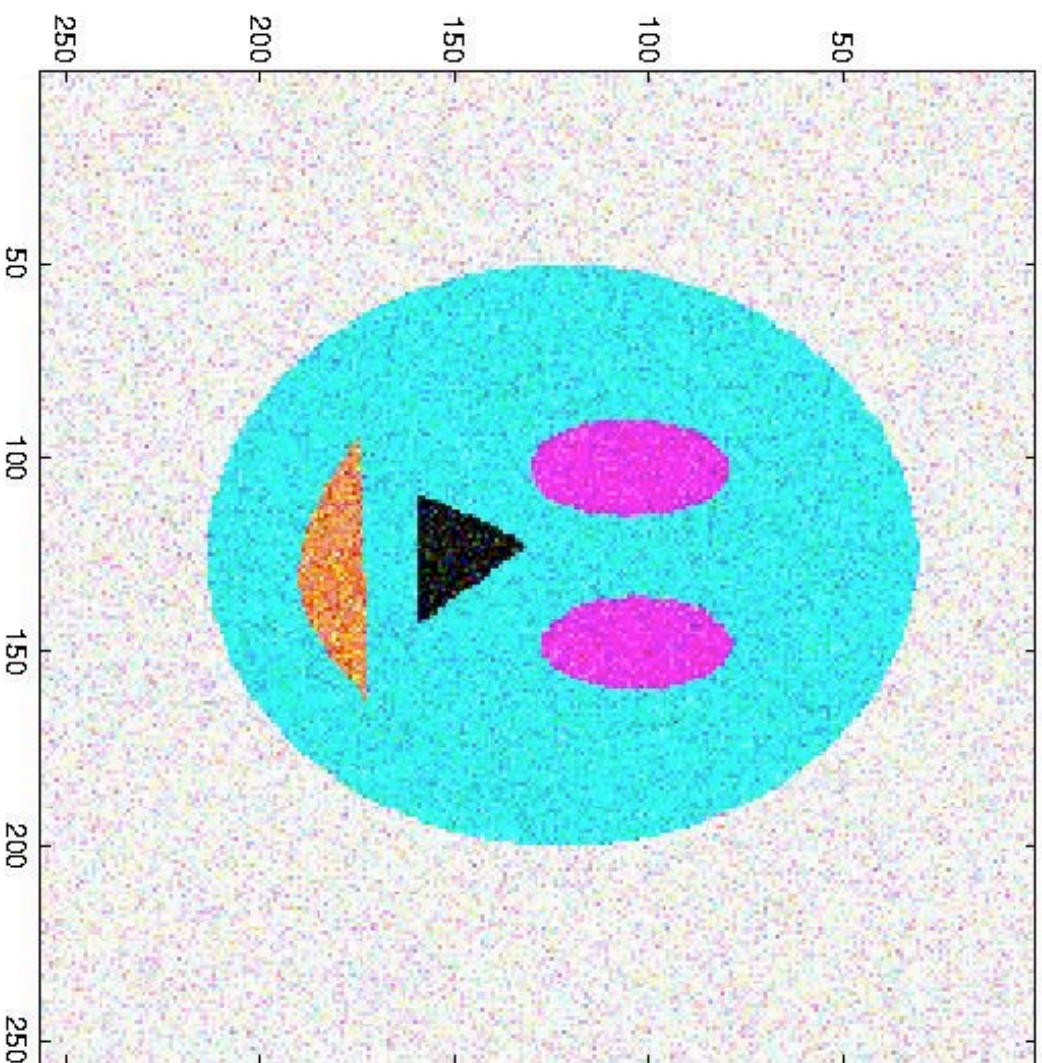
DB6, TV Hard Thresholding



4-level DB6, TV Hard thresholding, keep 64x64 coef.

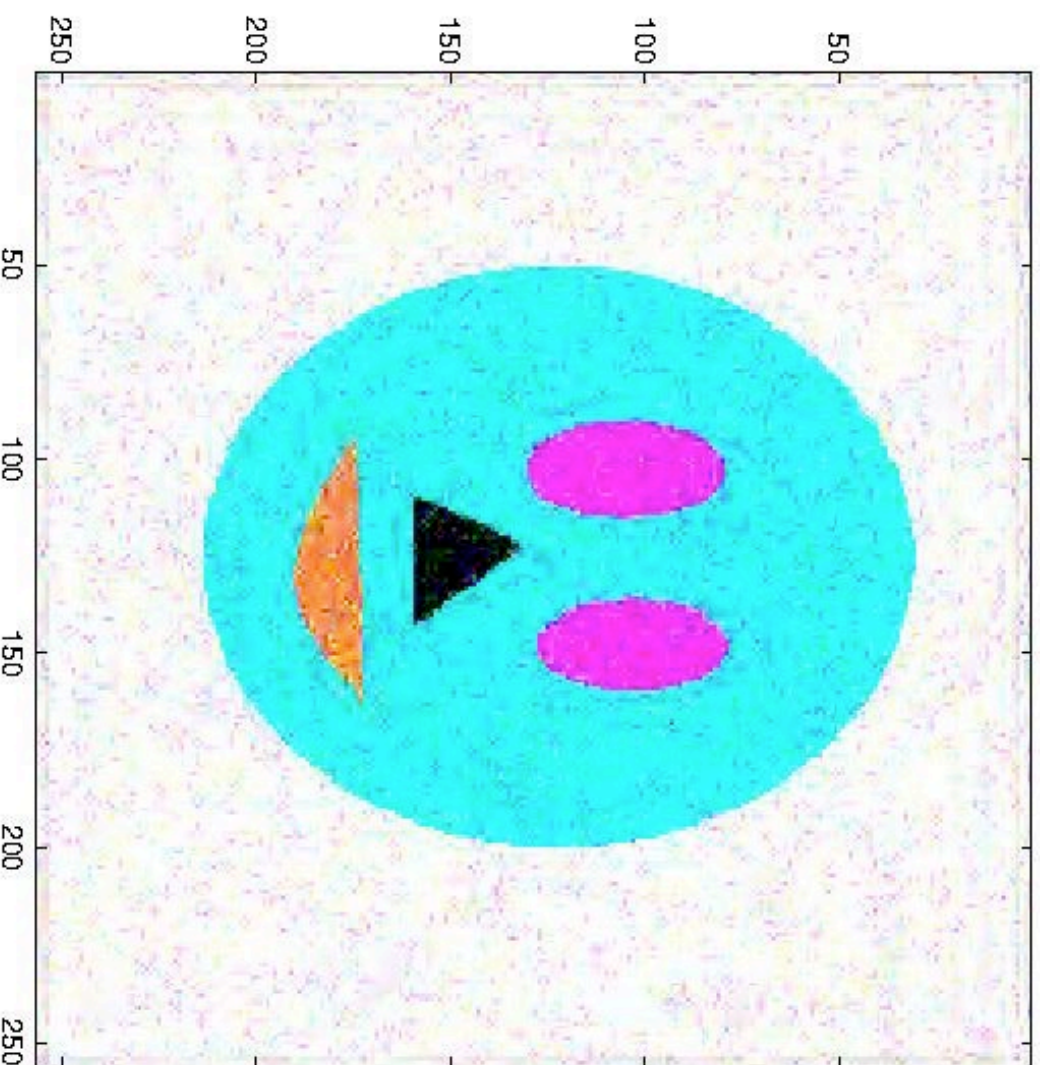
Original Noisy Image

Observed



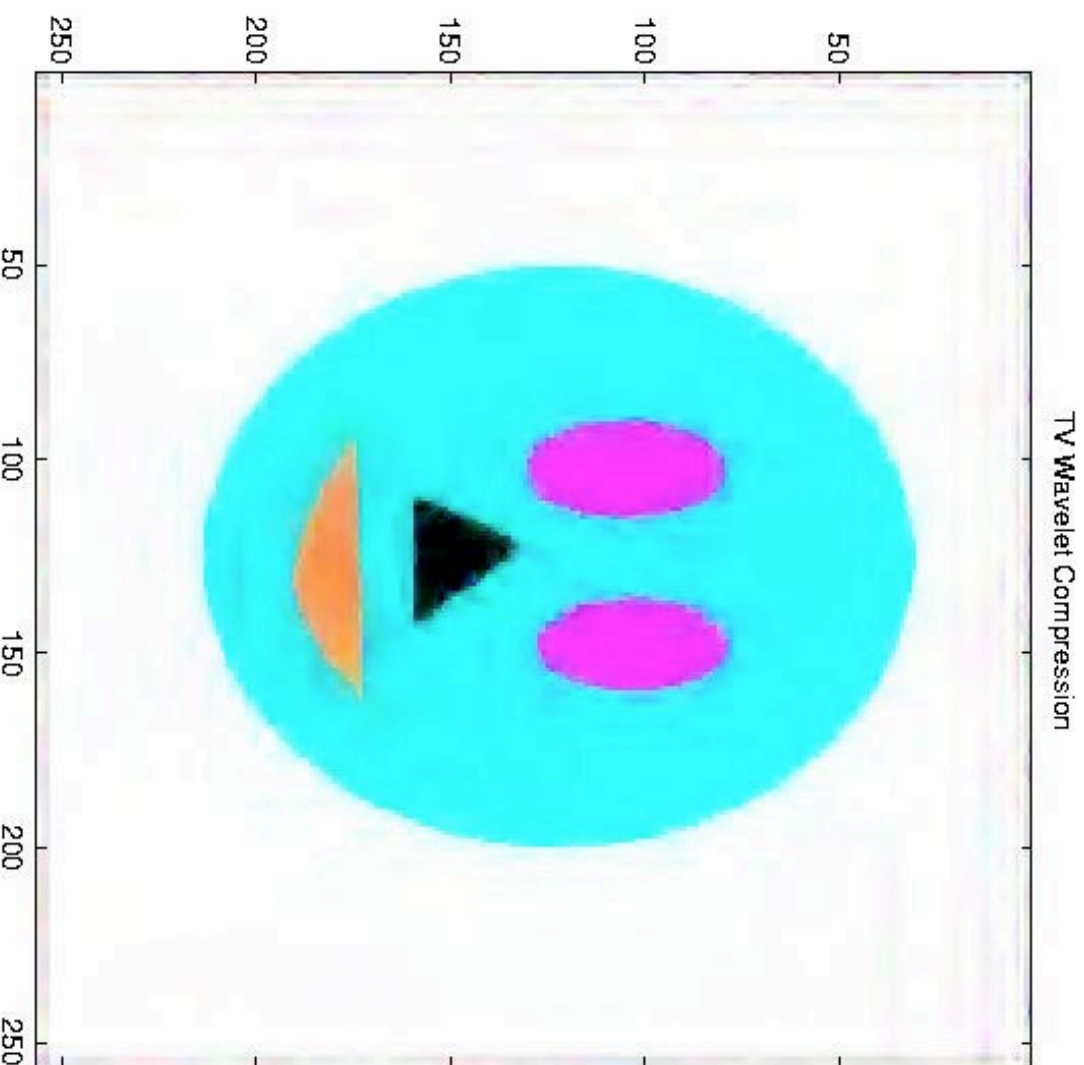
DB6, Hard Thresholding

Wavelet Hard Thresholding



4-level DB6, Hard thresholding, keep 64x64x3 coef.

DB6, TV Hard Thresholding



4-level DB6, TV Hard thresholding, keep 64x64x3 coef.

Wavelet Image inpainting

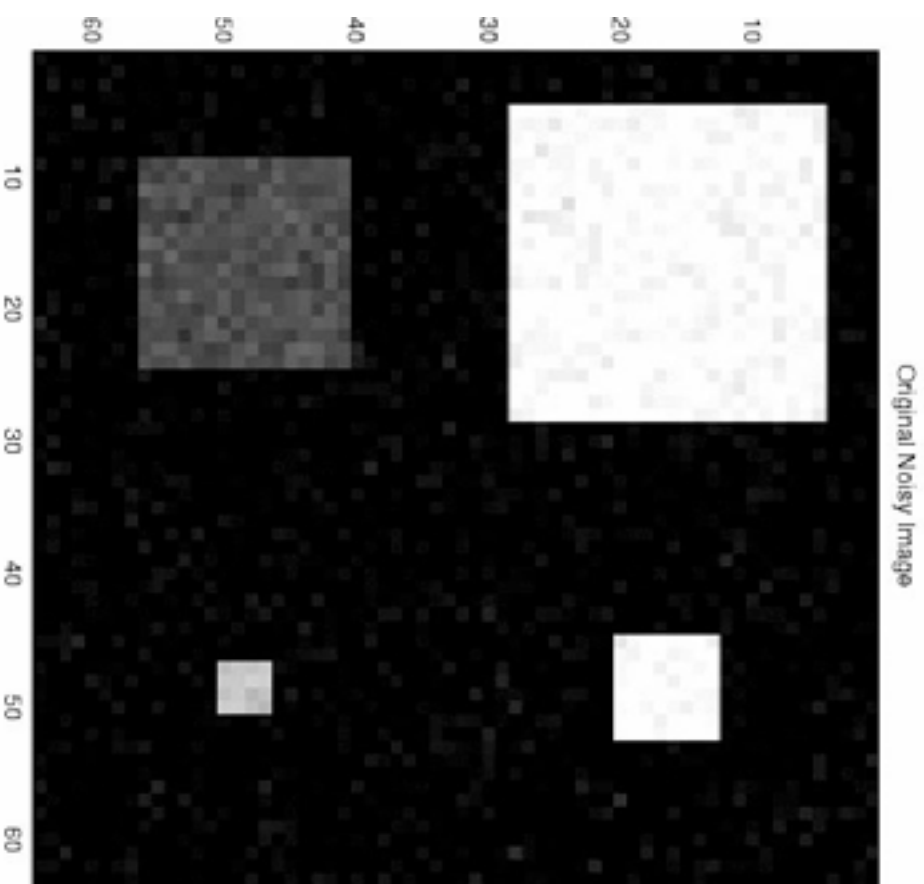
✗ Coefficients are damaged or lost in transmission

✗ Take ☐ to include all coefficients

✗ Minimize TV norm s.t. constraints only on retained coefficients, no constraint is imposed on the lost coefficients.

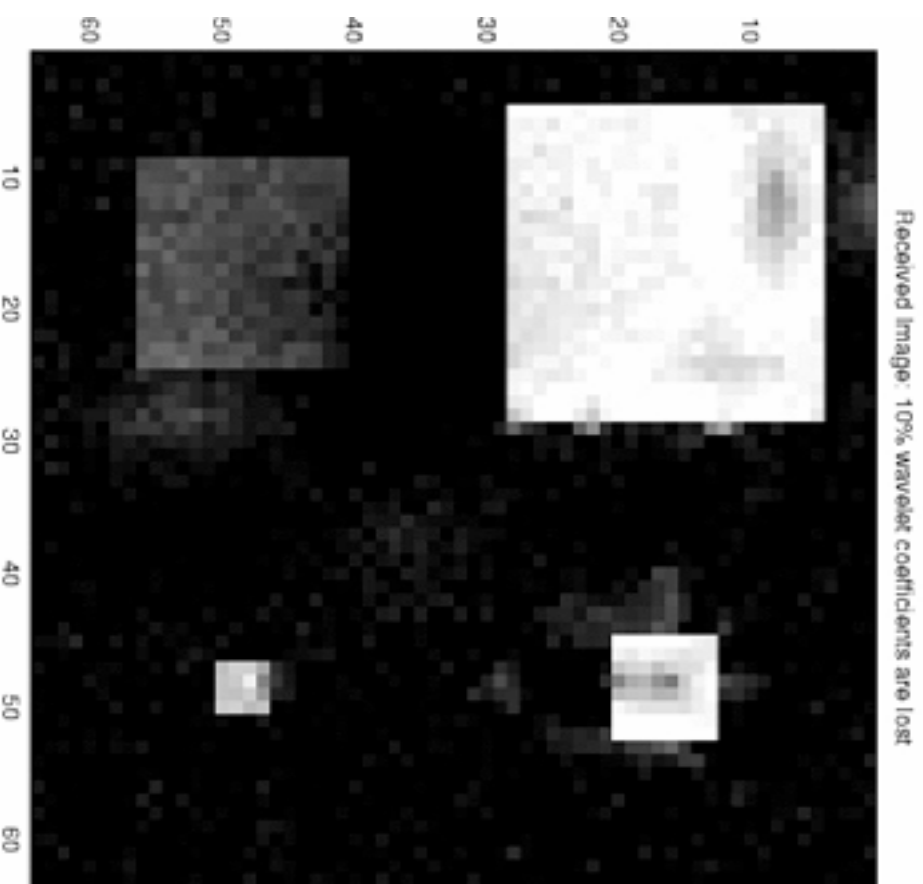
✗ Take ☐ if ☐ is lost,
otherwise ☐

Wavelet Image Inpainting



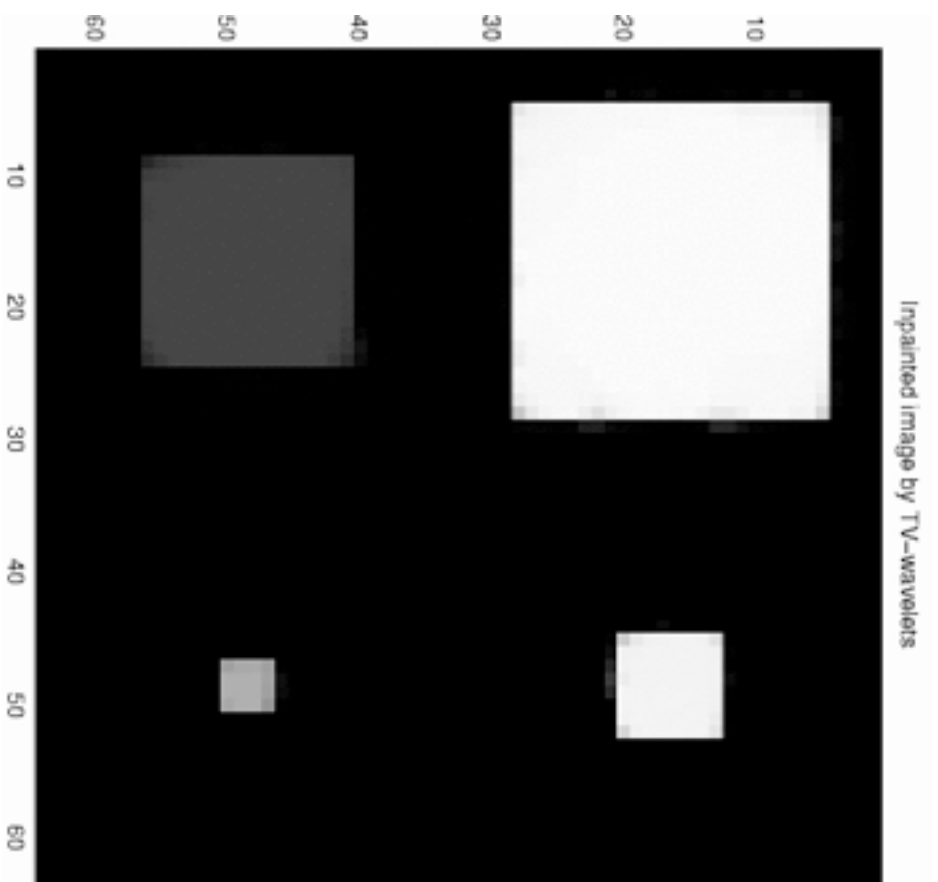
Original noisy test image

Wavelet Image inpainting



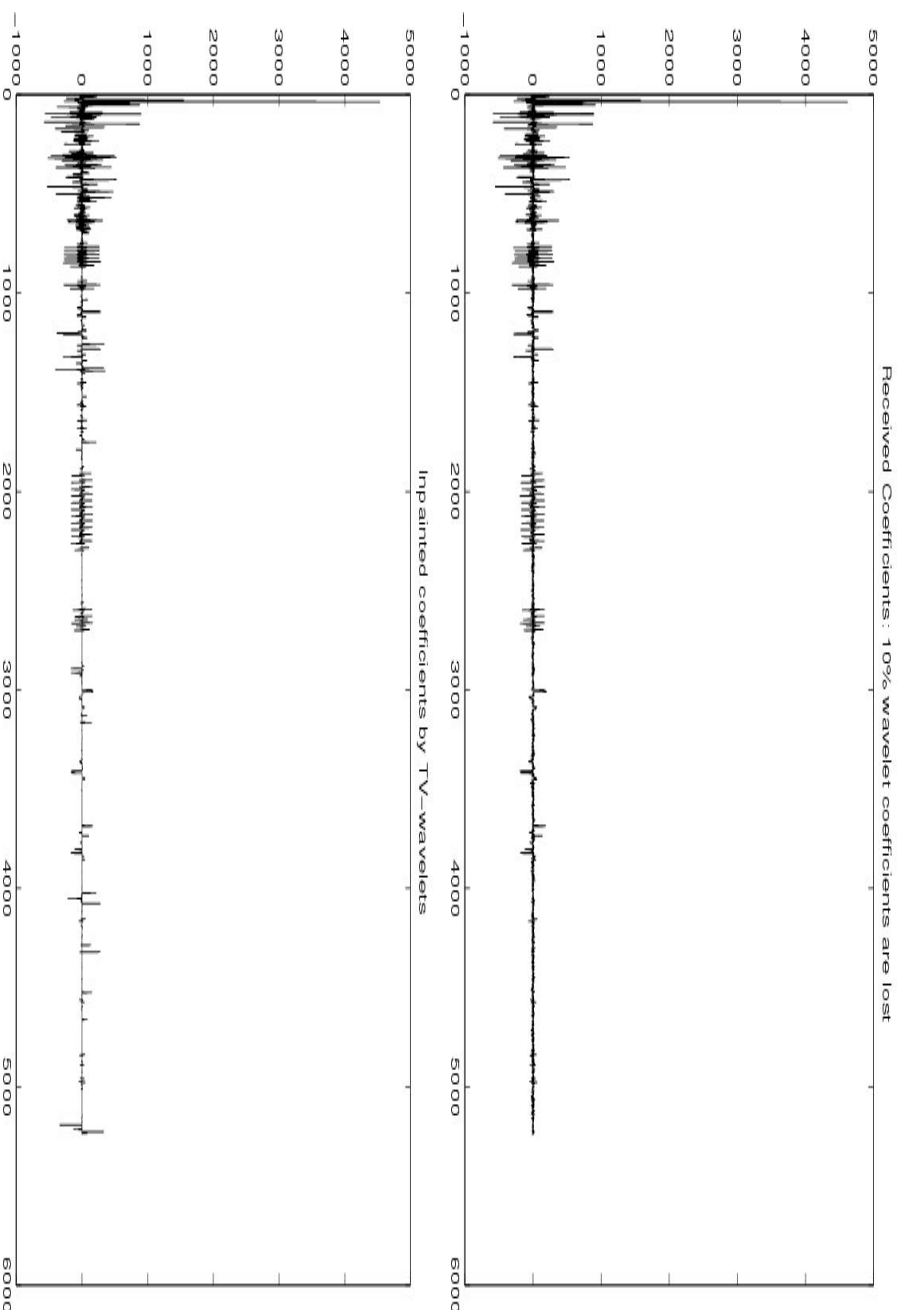
Received Image with 20% coefficients lost, particularly, some edges are damaged

Wavelet Image Inpainting



Inpainted image by minimizing TV norm, it reduced noise while filling in the edge shape

Wavelet Image Inpainting



Wavelet coefficients: lost (top), TV-norm inpainted (bottom)
Certain coefficients are significantly changed to min. TV norm

Conclusions

Topic 1: ENO-wavelets

Goals achieved: satisfies all goals:

Essentially Non-Oscillatory

Keep pyramidal filtering framework

Stability and error bound independent of discontinuities



Minimal extra cost (ratio $O(d/n)$) and storage ($O(1)$ bit/jump)

Generality: Can be applied to other wavelets

Application: incorporate ENO-wavelets in the optimization framework of GTW and achieve significant performance gain.

Topic 2: TV model for wavelet thresholding

Improve the denoising and compression in wavelet thresholding. Reduce the edge oscillations.